DS 4400

Machine Learning and Data Mining I Spring 2021

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Announcements

- HW2 is on Gradescope and Piazza, due on Friday, February 19
- Project resources on Piazza
- Project proposal due on March 4

Outline

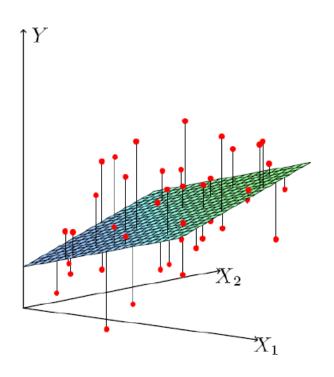
- Gradient Descent comparison with closedform solution for linear regression
- Regularization
 - Ridge regression and gradient descent update
 - Lasso regression
- Classification
 - K Nearest Neighbors (kNN)
 - Bias-Variance tradeoff

Multiple Linear Regression

- Dataset: $x_i \in \mathbb{R}^d$, $y_i \in \mathbb{R}$
- Hypothesis $h_{\theta}(x) = \theta^T x$
- MSE = $\frac{1}{N}\sum (\theta^T x_i y_i)^2$ Loss / cost

$$\boldsymbol{\theta} = (\boldsymbol{X}^\intercal \boldsymbol{X})^{-1} \boldsymbol{X}^\intercal \boldsymbol{y}$$

MSE is a strictly convex function and has unique minimum



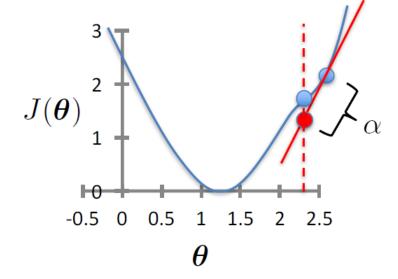
Gradient Descent

- Initialize θ
- Repeat until convergence

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\boldsymbol{\theta})$$

simultaneous update for j = 0 ... d

learning rate (small) e.g., $\alpha = 0.05$



Vector update rule: $\theta \leftarrow \theta - \alpha \frac{\partial J(\theta)}{\partial \theta}$

GD for Linear Regression

• Initialize θ

- $||\theta_{new} \theta_{old}|| < \epsilon$ or
- Repeat until convergence iterations == MAX_ITER

$$\theta_j \leftarrow \theta_j - \alpha \frac{2}{N} \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i) x_{ij}$$

simultaneous update for j = 0 ... d

- To achieve simultaneous update
 - At the start of each GD iteration, compute $h_{ heta}(x_i)$
 - Use this stored value in the update step loop
- Assume convergence when $\|oldsymbol{ heta}_{new} oldsymbol{ heta}_{old}\|_2 < \epsilon$

$$\| m{v} \|_2 = \sqrt{\sum_i v_i^2} = \sqrt{v_1^2 + v_2^2 + \ldots + v_{|v|}^2}$$

Gradient Descent in Practice

- Asymptotic complexity
 - N is size of training data, d is feature dimension, and T is number of iterations
- Most popular optimization algorithm in use today
- At the basis of training
 - Linear Regression
 - Logistic regression
 - SVM
 - Neural networks and Deep learning
 - Stochastic Gradient Descent variants

Gradient Descent vs Closed Form

Gradient Descent

- Initialize θ
- Repeat until convergence

$$\theta_j \leftarrow \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\boldsymbol{\theta})$$

simultaneous update for i = 0 ... d

Closed form

$$\boldsymbol{\theta} = (\boldsymbol{X}^\intercal \boldsymbol{X})^{-1} \boldsymbol{X}^\intercal \boldsymbol{y}$$

- Gradient Descent
- + Linear increase in d and N
- + Generally applicable
- Need to choose α and stopping conditions
- Might get stuck in local optima

- Closed Form
- + No parameter tuning
- + Gives the global optimum
- Not generally applicable
- Slow computation:

Issues with Gradient Descent

- Might get stuck in local optimum and not converge to global optimum
 - Restart from multiple initial points
- Only works with differentiable loss functions
- Small or large gradients
 - Feature scaling helps
- Tune learning rate
 - Can use line search for determining optimal learning rate

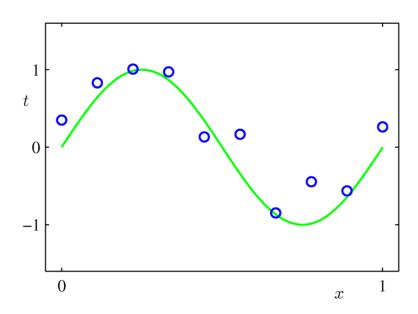
Review Gradient Descent

- Gradient descent is an efficient algorithm for optimization and training ML models
 - The most widely used algorithm in ML!
 - Much faster than using closed-form solution for linear regression
 - Main issues with Gradient Descent is convergence and getting stuck in local optima (for neural networks)
- Gradient descent is guaranteed to converge to optimum for strictly convex functions if run long enough

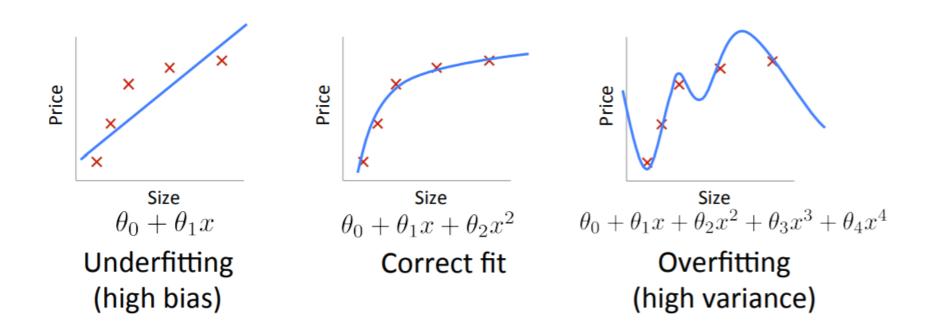
Polynomial Regression

Polynomial function on single feature

$$-h_{\theta}(x) = \theta_0 + \theta_1 x + \dots + \theta_p x^p$$



Polynomial Regression



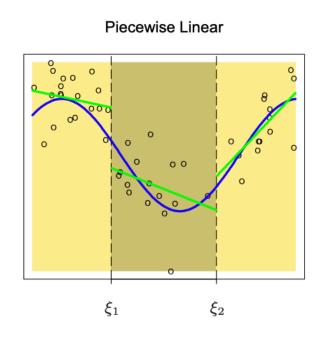
• Typically to avoid overfitting $d \leq 4$

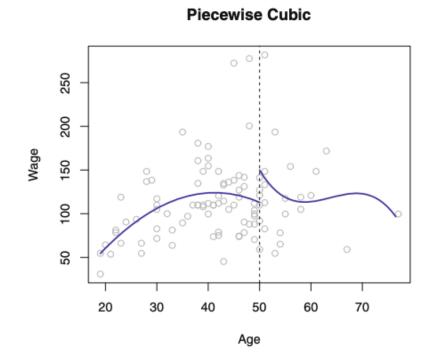
Polynomial Regression Training

- Simple Linear Regression
- $h_{\theta}(x) = \theta_0 + \theta_1 x + \dots + \theta_p x^p$
- How to train model?

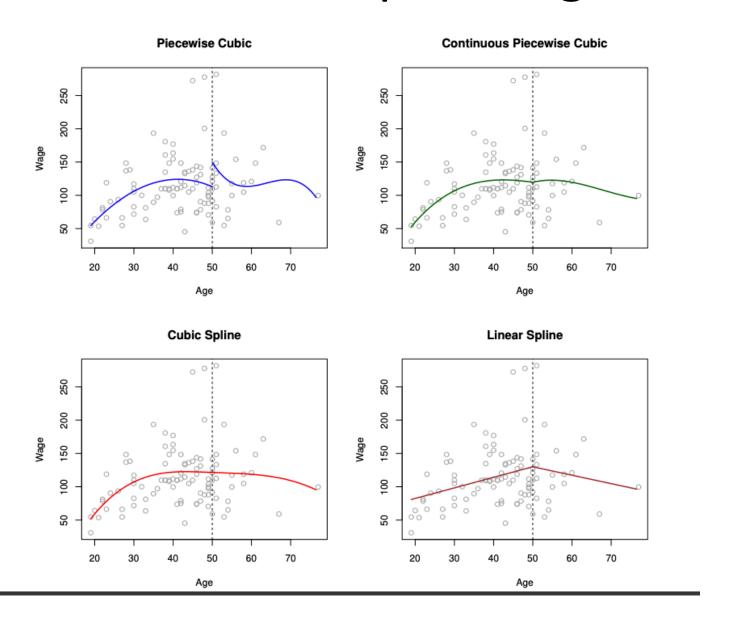
Piecewise Polynomial

- Divide the space into regions
- Polynomial regression on each region
 - Linear piecewise (degree 1), quadratic piecewise
 (degree 2), cubic piecewise (degree 3)

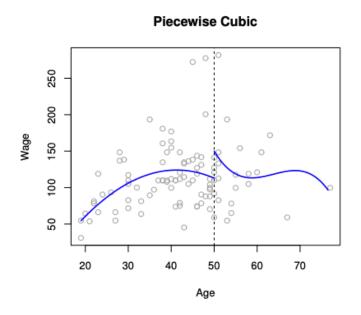


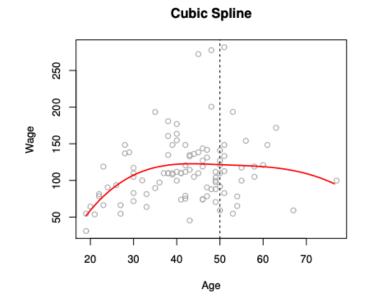


Piecewise and spline regression



Piecewise polynomial vs Regression spline





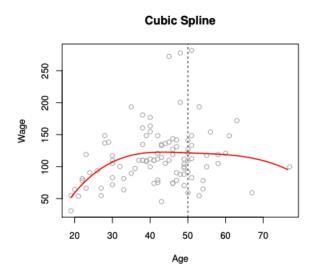
1 break at Age = 50

1 knot at Age = 50

Definition: Cubic spline

A cubic spline with knots at x-values ξ_1, \ldots, ξ_K is a continuous piecewise cubic polynomial with continuous derivates and continuous second derivatives at each knot.

Cubic splines



- ullet Turns out, cubic splines are sufficiently flexible to consistently estimate smooth regression functions f
- You can use higher-degree splines, but there's no need to
- To fit a cubic spline, we just need to pick the knots

A cubic spline with K knots has K+3 free parameters

Additive Models

Multiple Linear Regression Model

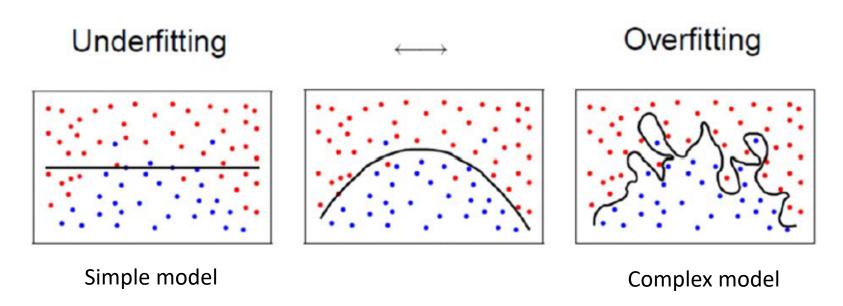
$$-y_i = \theta_0 + \theta_1 x_1 + \dots + \theta_d x_d$$

Additive Models

$$-y_i = \theta_0 + f_1(x_1) + \dots + f_d(x_d)$$

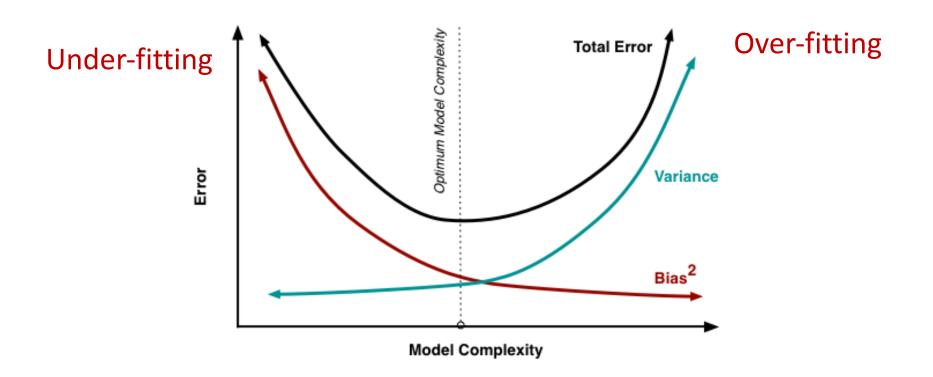
- Can instantiate functions f with:
 - Linear functions: $f_i(x_i) = \theta_i x_i$
 - Quadratic: $f_i(x_i) = \theta_i^1 x_i + \theta_i^2 x_i^2$
 - Cubic: $f_i(x_i) = \theta_i^1 x_i + \theta_i^2 x_i^2 + \theta_i^3 x_i^3$

Generalization in ML



- Goal is to generalize well on new testing data
- Risk of overfitting to training data

Bias-Variance Tradeoff



- Bias = Difference between estimated and true models
- Variance = Model difference on different training sets
 MSE is proportional to Bias + Variance

Regularization

- A method for automatically controlling the complexity of the learned hypothesis
- Idea: penalize for large values of θ_i
 - Can incorporate into the cost function
 - Works well when we have a lot of features, each that contributes a bit to predicting the label
- Can also address overfitting by eliminating features (either manually or via model selection)

Reduce model complexity
Reduce model variance

Ridge regression

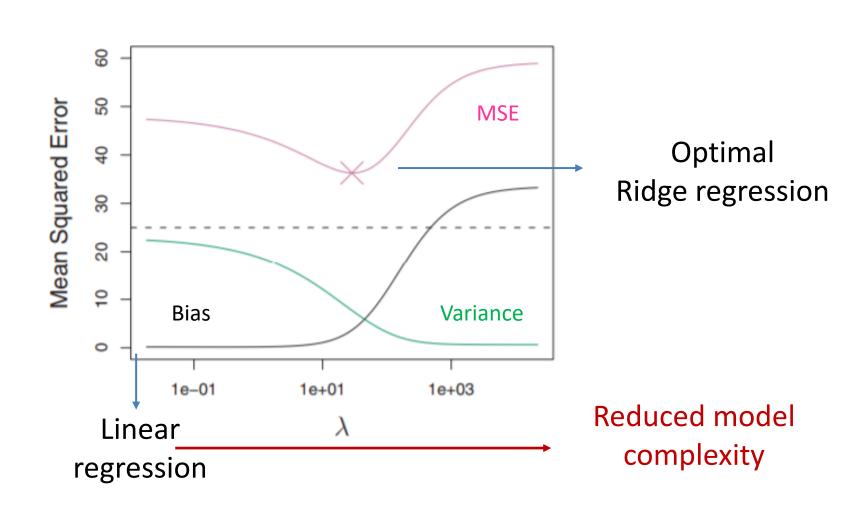
Linear regression objective function

$$J(\theta) = \frac{1}{2} \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i)^2 + \frac{\lambda}{2} \sum_{j=1}^{d} \theta_j^2$$

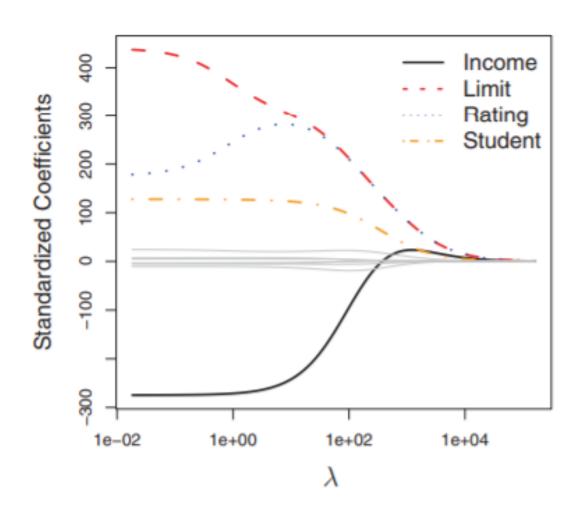
$$\text{model fit to data} \qquad \text{regularization}$$

- $-\lambda$ is the regularization parameter ($\lambda \geq 0$)
- No regularization on θ_0 !
 - If $\lambda = 0$, we train linear regression
 - If λ is large, the coefficients will shrink close to 0

Bias-Variance Tradeoff



Coefficient shrinkage



Predict credit card balance

GD for Ridge Regression

Min MSE

$$J(\theta) = \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i)^2 + \lambda \sum_{j=1}^{d} \theta_i^2$$

Gradient update: $\theta_0 \leftarrow \theta_0 - \alpha \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i)$

$$\theta_j \leftarrow \theta_j - \alpha \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i) x_{ij} - \alpha \lambda \theta_j$$

Regularization

$$\theta_j \leftarrow \theta_j (1 - \alpha \lambda) - \alpha \sum_{i=1}^N (h_{\theta}(x_i) - y_i) x_{ij}$$

Lasso Regression

$$J(\theta) = \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i)^2 + \lambda \sum_{j=1}^{d} |\theta_j|$$
Squared
Residuals

Regularization

- L1 norm for regularization
- Results in sparse coefficients
- Issue: gradients cannot be computed around 0
- Method of sub-gradient optimization

Alternative Formulations

Ridge

L2 Regularization

$$-\min_{\theta} \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i)^2 \text{ subject to } \sum_{j=1}^{d} |\theta_j|^2 \le \epsilon$$

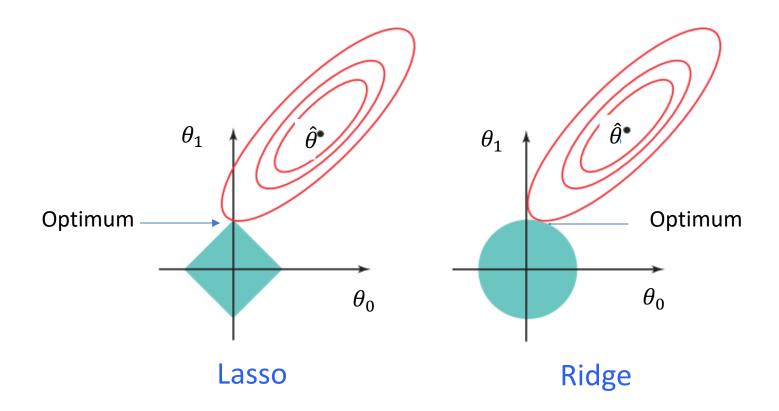
Lasso

- L1 regularization

$$-\min_{\theta} \sum_{i=1}^{N} (h_{\theta}(x_i) - y_i)^2$$
 subject to $\sum_{j=1}^{d} |\theta_j| \le \epsilon$

Lasso vs Ridge

- Ridge shrinks all coefficients
- Lasso sets some coefficients at 0 (sparse solution)
 - Perform feature selection



Ridge vs Lasso

- Both methods can be applied to any loss function (regression or classification)
- In both methods, value of regularization parameter λ needs to be adjusted
- Both reduce model complexity

Ridge

- + Differentiable objective
- Gradient descent converges to global optimum
- Shrinks all coefficients

Lasso

- Gradient descent needs to be adapted
- + Results in sparse model
- Can be used for feature selection in large dimensions