

DS 4400

Machine Learning and Data Mining I Spring 2021

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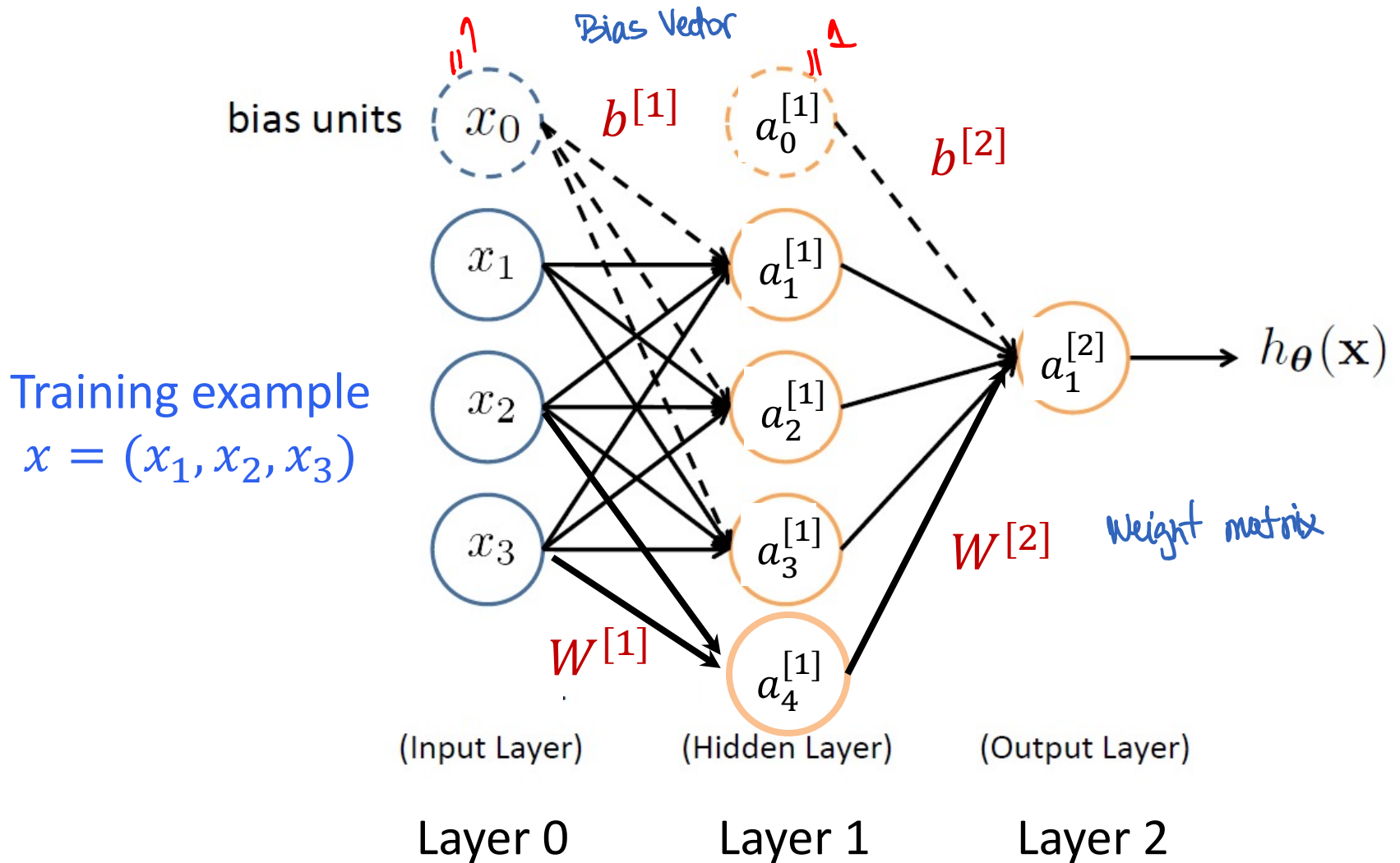
Northeastern University

March 25 2021

Outline

- Keras tutorial on feed-forward neural networks
- Convolutional neural networks
 - Convolution operation
 - Max pooling
 - Estimating parameters
- Architectures for convolutional networks
- Lab in Keras on convolutional networks

Feed-Forward Neural Network

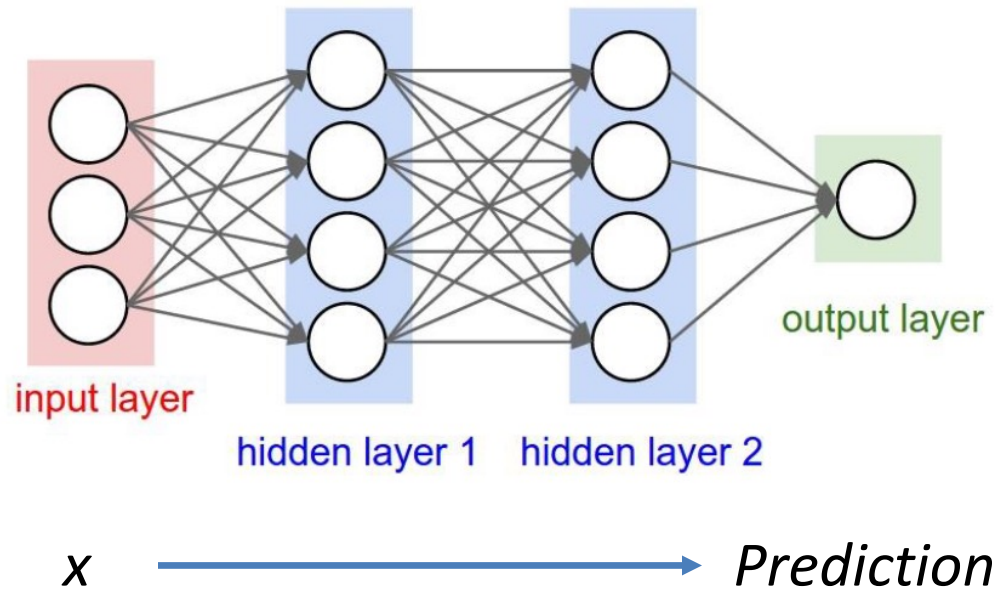


No cycles

$$\theta = (b^{[1]}, W^{[1]}, b^{[2]}, W^{[2]})$$

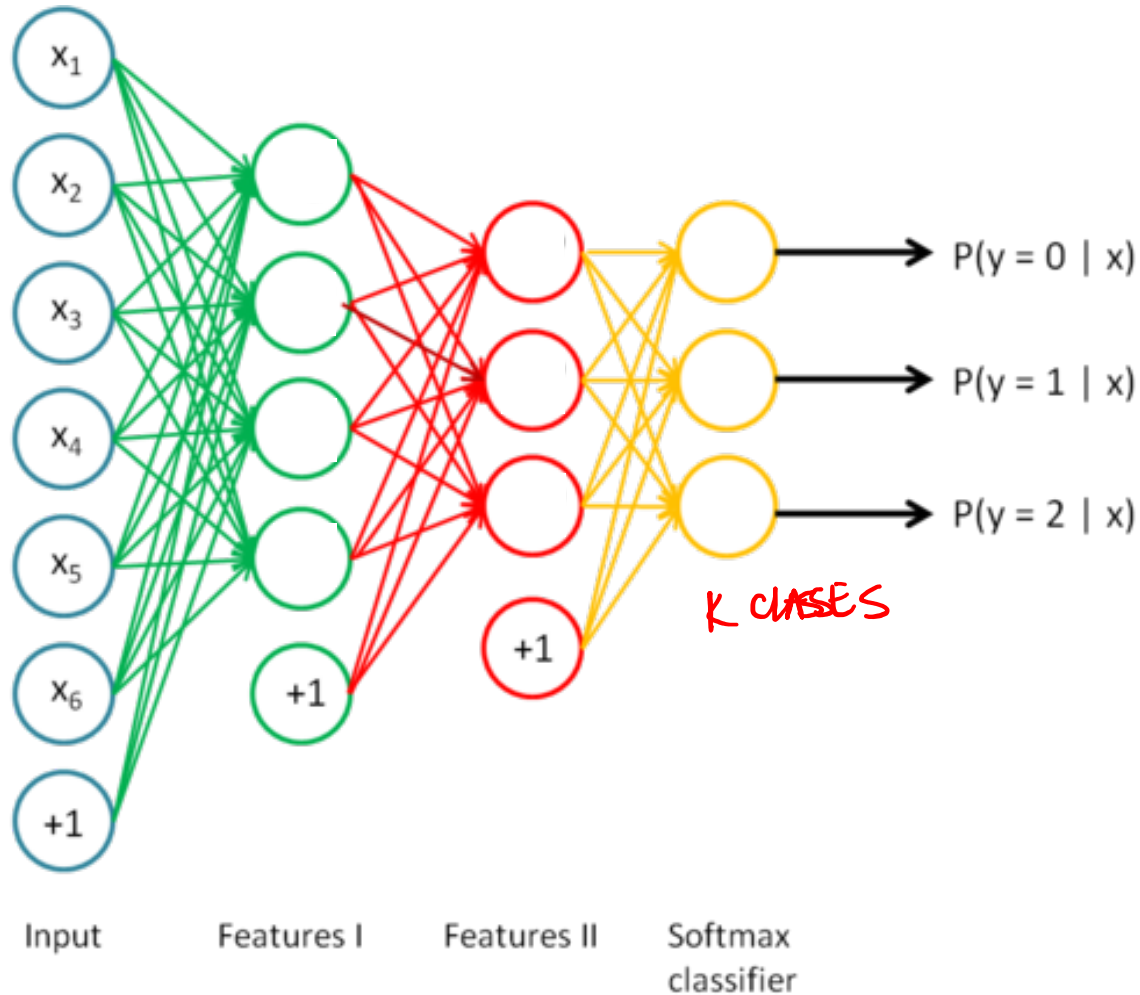
Forward Propagation

- The input neurons first receive the data features of the object. After processing the data, they send their output to the first hidden layer.
- The hidden layer processes this output and sends the results to the next hidden layer.
- This continues until the data reaches the final output layer, where the output value determines the object's classification.
- This entire process is known as **Forward Propagation**, or **Forward prop.**

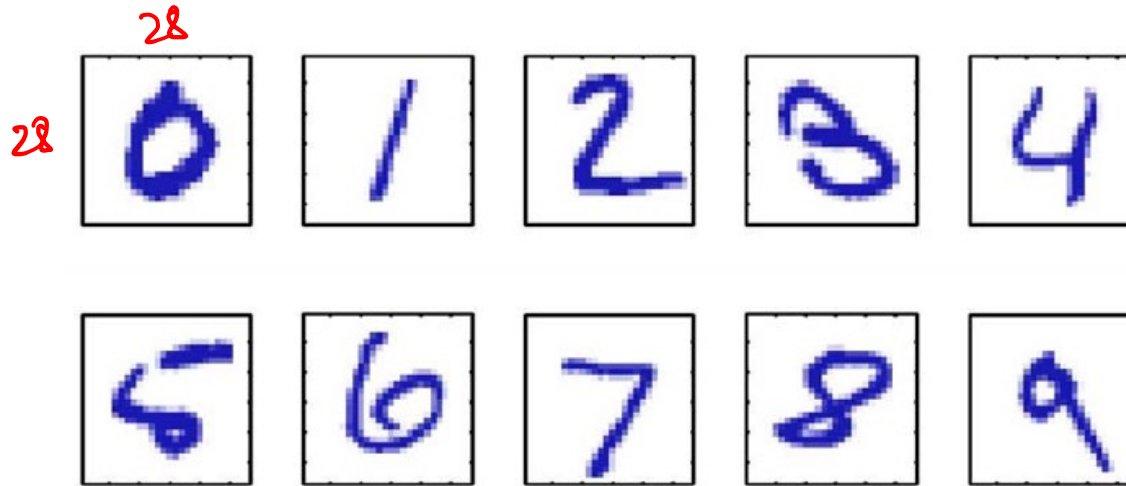


Multi-class classification

MULTI-LAYER PERCEPTRON (MLP)



MNIST: Handwritten digit recognition



Images are 28 x 28 pixels

Represent input image as a vector $\mathbf{x} \in \mathbb{R}^{784}$

Learn a classifier $f(\mathbf{x})$ such that,

$$f : \mathbf{x} \rightarrow \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$$

Predict the digit
Multi-class classifier

Lab – Feed Forward NN

```
import time
import numpy as np
#!pip install tensorflow
#!pip install keras

from keras.utils import np_utils
import keras.callbacks as cb
from keras.models import Sequential
from keras.layers.core import Dense, Dropout, Activation
from keras.optimizers import RMSprop
from keras.datasets import mnist

import matplotlib
import matplotlib.pyplot as plt
```

Import modules

```
def load_data():
    print("Loading data")
    (X_train, y_train), (X_test, y_test) = mnist.load_data()

    X_train = X_train.astype('float32')
    X_test = X_test.astype('float32')

    # Normalize
    X_train /= 255
    X_test /= 255

    y_train = np_utils.to_categorical(y_train, 10)
    y_test = np_utils.to_categorical(y_test, 10)

    X_train = np.reshape(X_train, (60000, 784))
    X_test = np.reshape(X_test, (10000, 784))

    print("Data loaded")
    return [X_train, X_test, y_train, y_test]
```

Load MNIST data
Processing

Vector
representation

Neural Network Architecture

```
def init_model1():
    start_time = time.time()

    print("Compiling Model")
    model = Sequential()
    model.add(Dense(10, input_dim=784))
    model.add(Activation('relu'))

    model.add(Dense(10))
    model.add(Activation('softmax'))

    rms = RMSprop()
    model.compile(loss='categorical_crossentropy', optimizer=rms, metrics=['accuracy'])

    print("Model finished "+format(time.time() - start_time))
    return model
```

10 hidden units
ReLU activation

Output Layer
Softmax activation

Loss function

Optimizer

Feed-Forward Neural Network Architecture

- 1 Hidden Layer (“Dense” or Fully Connected)
- 10 neurons
- Output layer uses softmax activation

Number of Parameters

```
model.summary()
```

Model: "sequential_6"

Layer (type)	Output Shape	Param #
=====		
dense_16 (Dense)	(None, 10)	7850
<hr/>		
activation_16 (Activation)	(None, 10)	0
<hr/>		
dense_17 (Dense)	(None, 10)	110
<hr/>		
activation_17 (Activation)	(None, 10)	0
=====		

Total params: 7,960

Trainable params: 7,960

Non-trainable params: 0

Train and evaluate

```
def run_network(data=None, model=None, epochs=20, batch=256):
    try:
        start_time = time.time()
        if data is None:
            X_train, X_test, y_train, y_test = load_data()
        else:
            X_train, X_test, y_train, y_test = data

        print("Training model")
        history = model.fit(X_train, y_train, epochs=epochs, batch_size=batch,
                           validation_data=(X_test, y_test), verbose=2)

        print("Training duration:"+format(time.time() - start_time))
        score = model.evaluate(X_test, y_test, batch_size=16)

        print("\nNetwork's test loss and accuracy:"+format(score))
        return history
    except KeyboardInterrupt:
        print("KeyboardInterrupt")
        return history
```

Training/testing results

```
Epoch 98/100  
235/235 - 0s - loss: 0.1611 - accuracy: 0.9552 - val_loss: 0.2329 - val_accuracy: 0.9411  
Epoch 99/100  
235/235 - 0s - loss: 0.1609 - accuracy: 0.9550 - val_loss: 0.2334 - val_accuracy: 0.9392  
Epoch 100/100  
235/235 - 0s - loss: 0.1603 - accuracy: 0.9550 - val_loss: 0.2323 - val_accuracy: 0.9401  
Training duration: 22.163272857666016  
625/625 [=====] - 1s 711us/step - loss: 0.2323 - accuracy: 0.9401  
  
Network's test loss and accuracy: [0.23233847320079803, 0.9401000142097473]
```

Changing Number of Neurons

```
def init_model2():
    start_time = time.time()

    print("Compiling Model")
    model = Sequential()
    model.add(Dense(500, input_dim=784))
    model.add(Activation('relu'))

    model.add(Dense(10))
    model.add(Activation('softmax'))

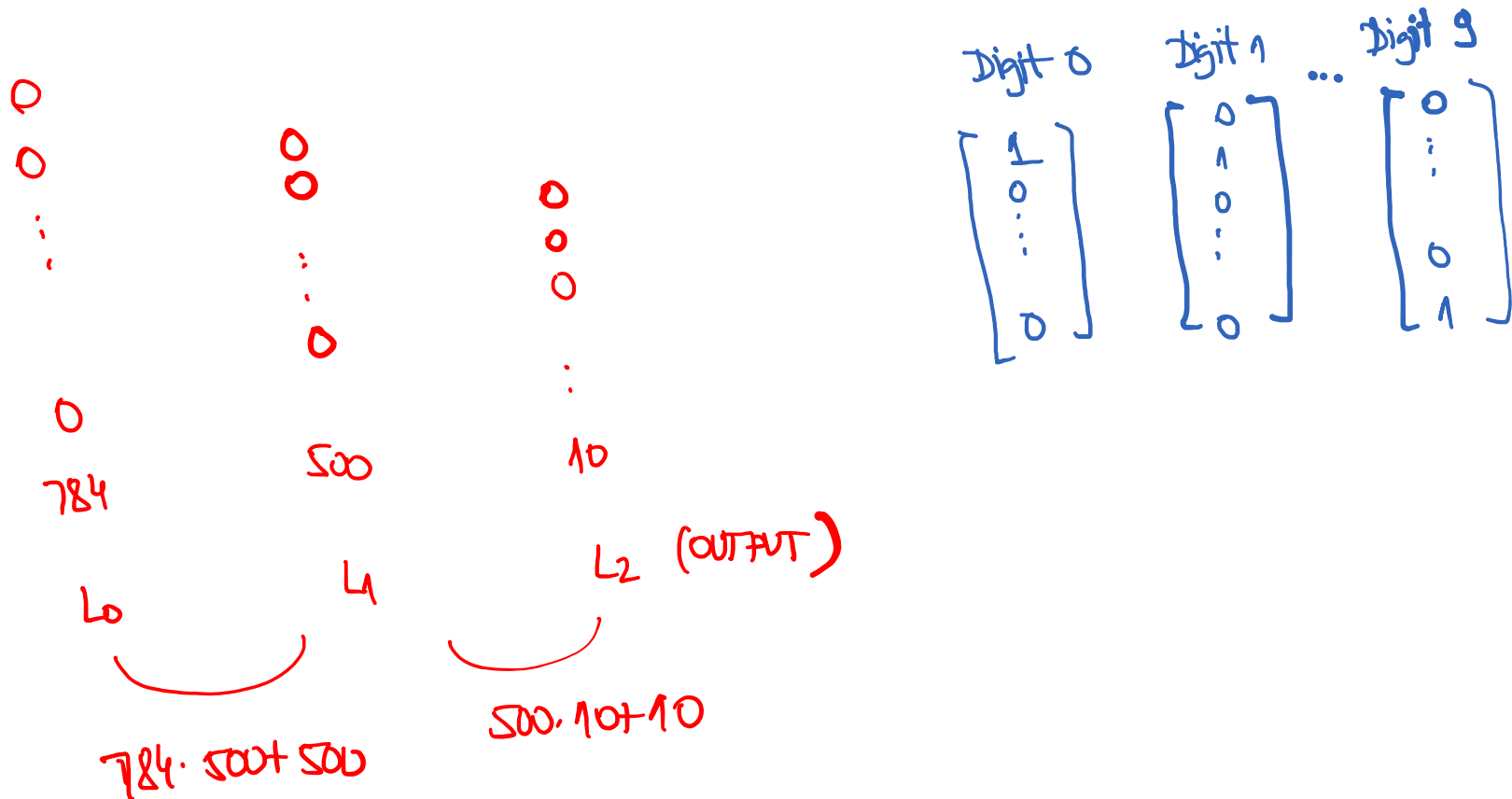
    rms = RMSprop()
    model.compile(loss='categorical_crossentropy', optimizer=rms, metrics=['accuracy'])

    print("Model finished "+format(time.time() - start_time))
    return model
```

```
Epoch 98/100
235/235 - 1s - loss: 1.1261e-08 - accuracy: 1.0000 - val_loss: 0.1432 - val_accuracy: 0.9835
Epoch 99/100
235/235 - 1s - loss: 1.1088e-08 - accuracy: 1.0000 - val_loss: 0.1432 - val_accuracy: 0.9834
Epoch 100/100
235/235 - 1s - loss: 1.0918e-08 - accuracy: 1.0000 - val_loss: 0.1435 - val_accuracy: 0.9835
Training duration: 82.20909094810486
625/625 [=====] - 1s 932us/step - loss: 0.1435 - accuracy: 0.9835

Network's test loss and accuracy:[0.1434623748064041, 0.9835000038146973]
```

Number of Parameters



Number of Parameters

```
model2.summary()
```

Model: "sequential_9"

Layer (type)	Output Shape	Param #
=====	=====	=====
dense_22 (Dense)	(None, 500)	392500
activation_22 (Activation)	(None, 500)	0
dense_23 (Dense)	(None, 10)	5010
activation_23 (Activation)	(None, 10)	0
=====	=====	=====
Total params: 397,510		
Trainable params: 397,510		
Non-trainable params: 0		

Two Layers

```
def init_model4():
    start_time = time.time()

    print("Compiling Model")
    model = Sequential()
    model.add(Dense(500, input_dim=784))
    model.add(Activation('relu'))
    model.add(Dropout(0.4))
    model.add(Dense(300))
    model.add(Activation('relu'))
    model.add(Dropout(0.4))
    model.add(Dense(10))
    model.add(Activation('softmax'))

    rms = RMSprop()
    model.compile(loss='categorical_crossentropy', optimizer=rms, metrics=['accuracy'])

    print("Model finished"+format(time.time() - start_time))
    return model
```

```
235/235 - 1s - loss: 0.0164 - accuracy: 0.9961 - val_loss: 0.1677 - val_accuracy: 0.9844
Epoch 98/100
235/235 - 1s - loss: 0.0164 - accuracy: 0.9961 - val_loss: 0.1677 - val_accuracy: 0.9844
Epoch 99/100
235/235 - 1s - loss: 0.0146 - accuracy: 0.9966 - val_loss: 0.1701 - val_accuracy: 0.9841
Epoch 100/100
235/235 - 1s - loss: 0.0134 - accuracy: 0.9968 - val_loss: 0.1666 - val_accuracy: 0.9849
Training duration: 131.49207520484924
625/625 [=====] - 1s 1ms/step - loss: 0.1666 - accuracy: 0.9849
```

Network's test loss and accuracy:[0.16656503081321716, 0.9848999977111816]

Number of Parameters

0	0	0	0
0	0	0	0
:	:	:	:
:	:	:	:
0	0	0	0
0	0	0	0
784	500	300	10
L_0	L_1	L_2	L_3

Model Parameters

```
model4.summary()
```

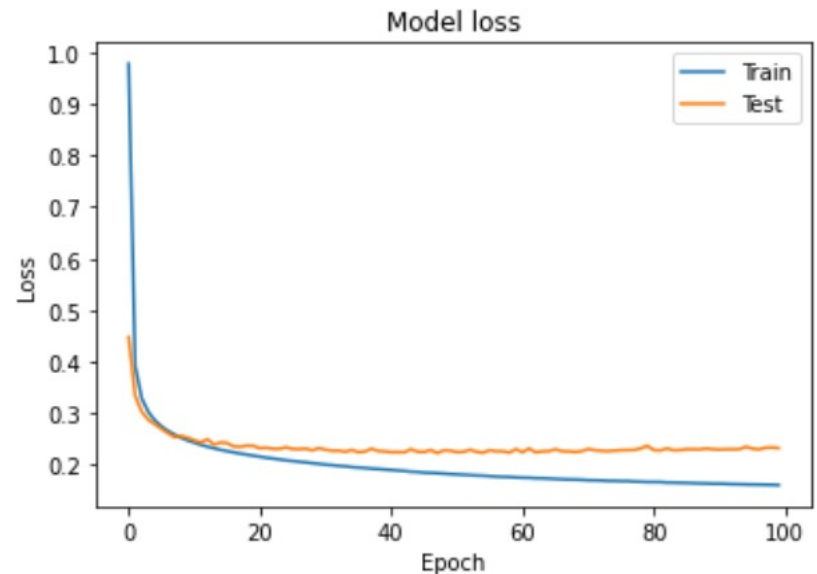
Model: "sequential_11"

Layer (type)	Output Shape	Param #
dense_26 (Dense)	(None, 500)	392500 <i>L₀→L₁</i>
activation_26 (Activation)	(None, 500)	0
dropout_9 (Dropout)	(None, 500)	0
dense_27 (Dense)	(None, 300)	150300 <i>L₁→L₂</i>
activation_27 (Activation)	(None, 300)	0
dropout_10 (Dropout)	(None, 300)	0
dense_28 (Dense)	(None, 10)	3010 <i>L₂→L₃</i>
activation_28 (Activation)	(None, 10)	0
Total params: 545,810		
Trainable params: 545,810		
Non-trainable params: 0		

Monitor Loss

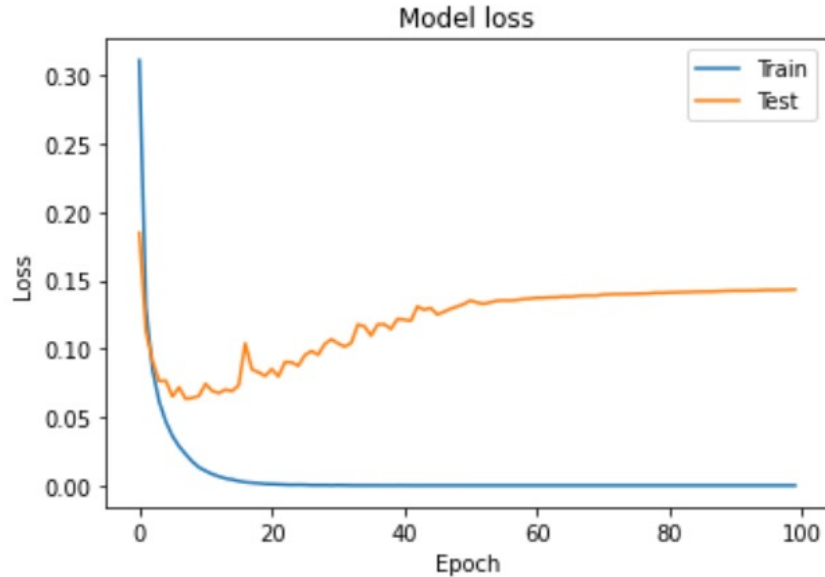
```
def plot_losses(hist):  
    plt.plot(hist.history['loss'])  
    plt.plot(hist.history['val_loss'])  
    plt.title('Model loss')  
    plt.ylabel('Loss')  
    plt.xlabel('Epoch')  
    plt.legend(['Train', 'Test'], loc='upper right')  
    plt.show()
```

```
modell = init_model1()  
  
history1 = run_network(model = modell, epochs=100)  
  
plot_losses(history1)
```

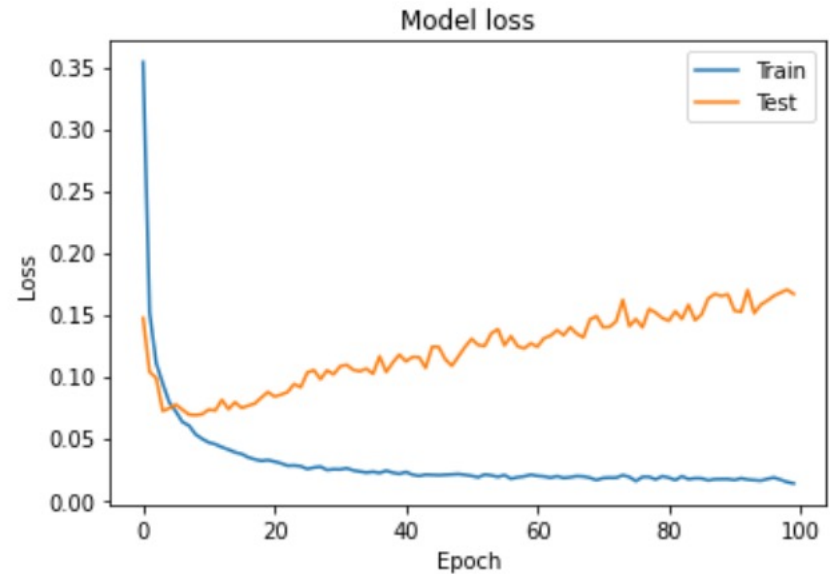


Loss

```
model2 = init_model2()  
  
history2 = run_network(model = model2, epochs=100)  
  
plot_losses(history2)
```



```
model4 = init_model4()  
  
history4 = run_network(model = model4, epochs=100)  
  
plot_losses(history4)
```



Review FFNN

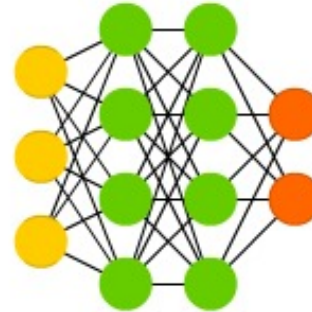
- Feed-Forward Neural Networks are the common neural networks architectures
 - Fully connected networks are called Multi-Layer Perceptron
- Input, output, and hidden layers
 - Linear matrix operations followed by non-linear activations at every layer
- Activations:
 - ReLU, tanh, etc., for hidden layers
 - Sigmoid (binary classification) and softmax (for multi-class classification) at last layer
- Forward propagation: process of evaluating input through the network

Neural Network Architectures

Feed-Forward Networks

- Neurons from each layer connect to neurons from next layer

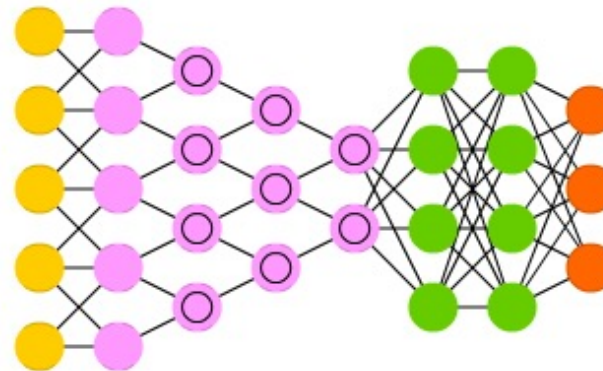
Deep Feed Forward (DFF)



Convolutional Networks

- Includes convolution layer for feature reduction
- Learns hierarchical representations

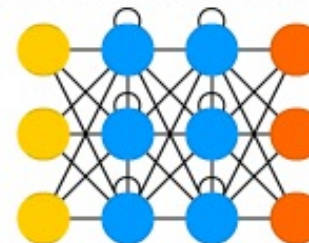
Deep Convolutional Network (DCN)



Recurrent Networks

- Keep hidden state
- Have cycles in computational graph

Recurrent Neural Network (RNN)

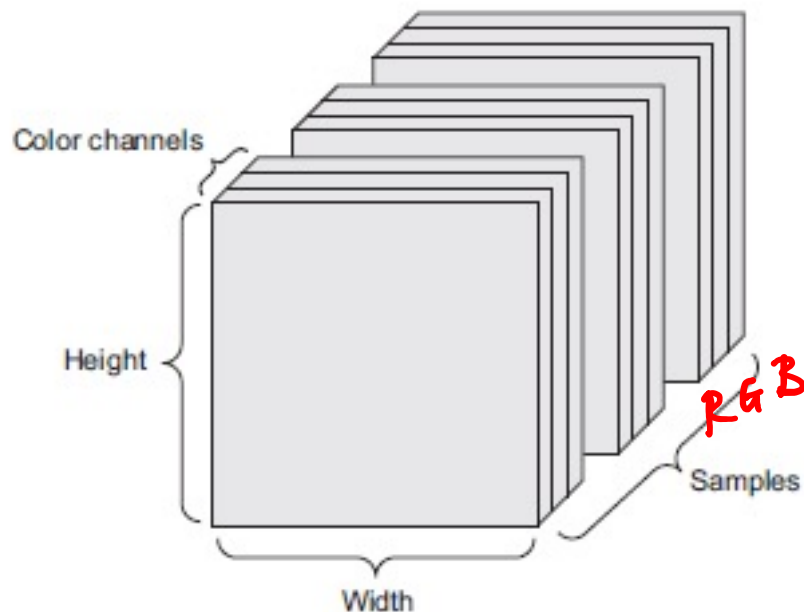


Convolutional Nets

- Particular type of Feed-Forward Neural Nets
 - Invented by [LeCun 89]
- Applicable to data with natural grid topology
 - Time series
 - Images
- Use convolutions on at least one layer
 - Convolution is a linear operation that uses local information
 - Also use pooling operation
 - Used for dimensionality reduction and learning hierarchical feature representations

Image Representation

- Image is 3D “tensor”: height, width, color channel (RGB)
- Black-and-white images are 2D matrices: height, width
 - Each value is pixel intensity

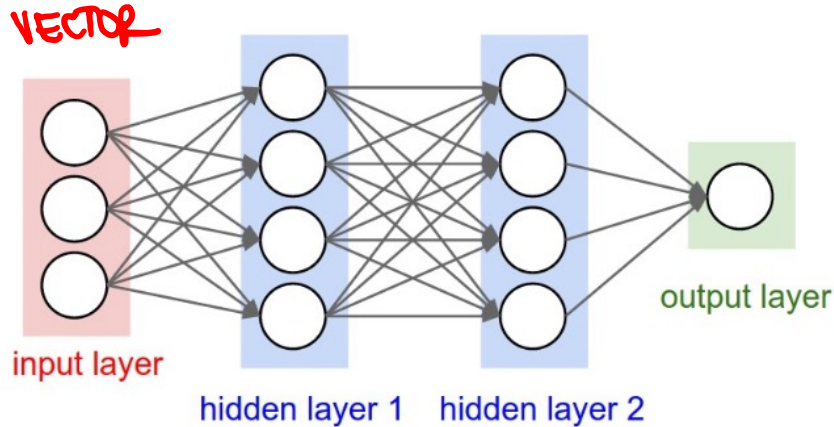


Computer vision principles

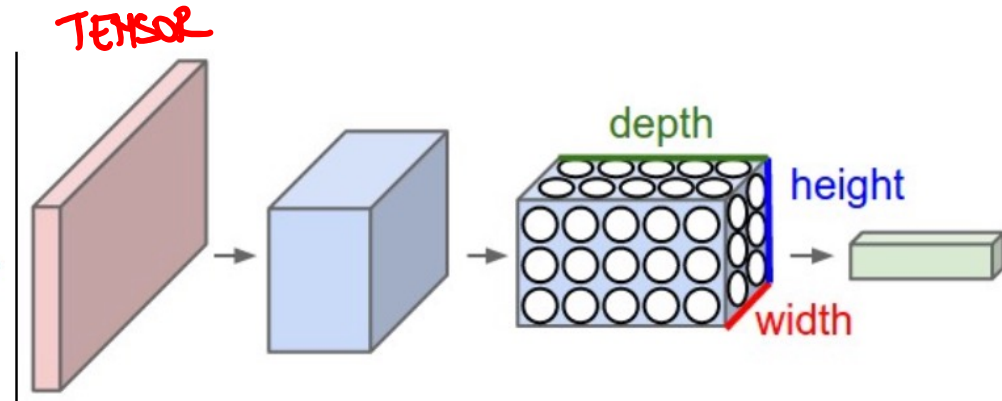
- Task: image classification (object identification)
- Translation invariance
 - Classification should work if object appears in different locations in the image => All image regions are treated the same
- Locality
 - Focus on local regions for object detection => computation should be local
- Mathematical operation: Convolution

Convolutional Neural Networks

Feed-forward network

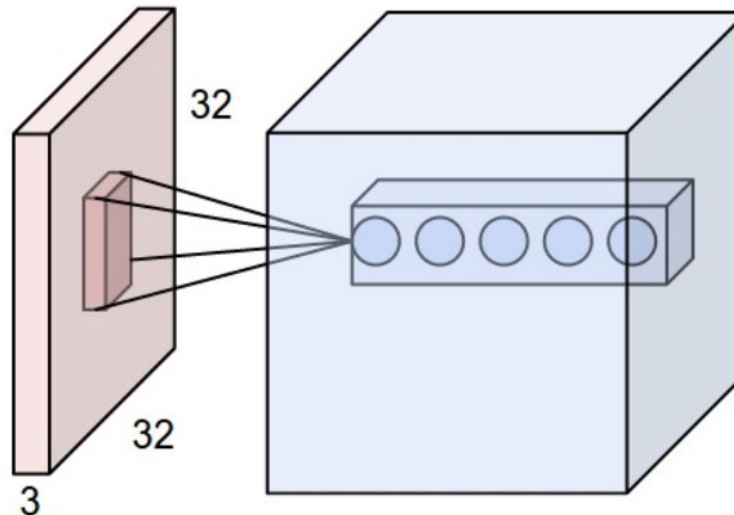


Convolutional network

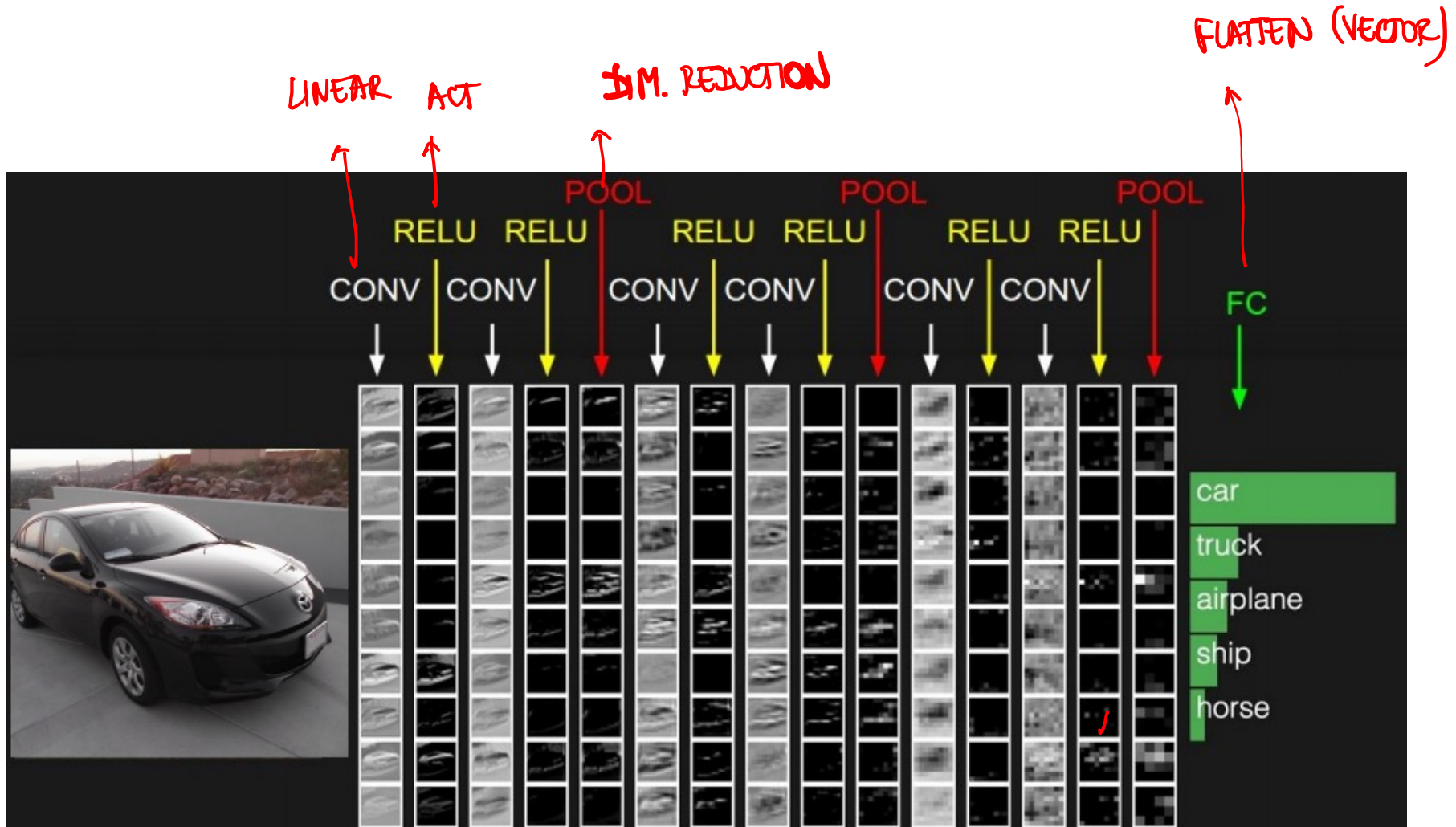


Filter

3D TENSOR

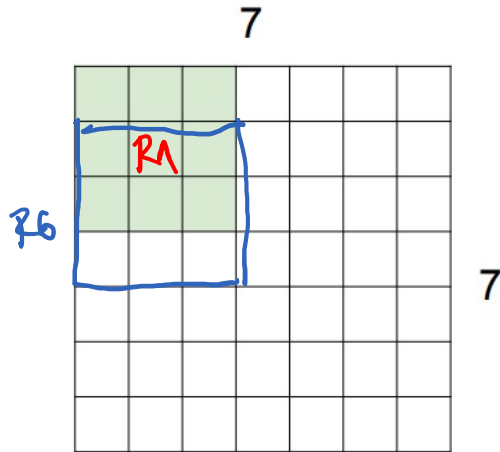


Convolutional Nets

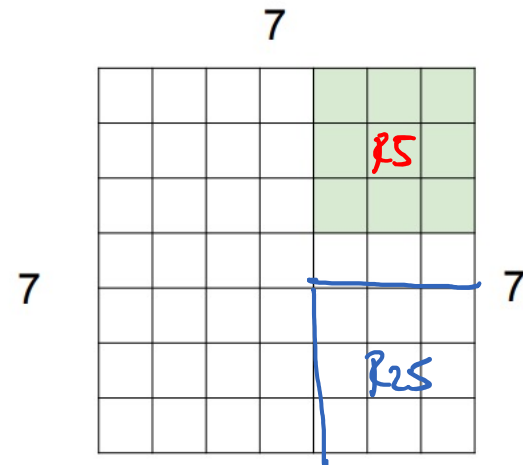
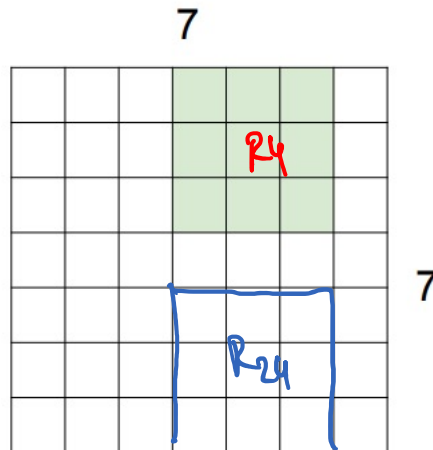
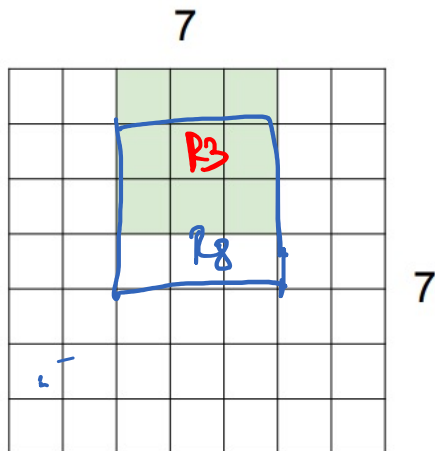
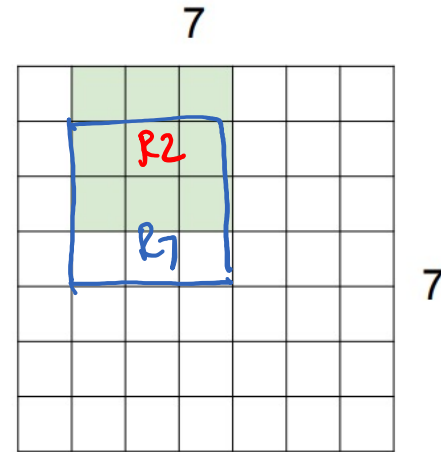


Convolutions ^{2D}

A closer look at spatial dimensions:



7x7 input (spatially)
assume 3x3 filter



OUTPUT

R ₁	R ₂	R ₃	R ₄	R ₅
R ₆	R ₇	R ₈		
			R ₂₄	R ₂₅

Example

BLAST

	r_1	r_2
0	1	2
3	4	5
6	7	8

*

0	1
2	3

=

$$\begin{bmatrix} 19 & 25 \\ 37 & 43 \end{bmatrix}$$

LEARNED DURING
TRAINING

Input

Filter

Output

r_1

0	1	3	4
---	---	---	---

• DOT

FILTER

0	1	2	3
---	---	---	---

||

$$0 \cdot 0 + 1 \cdot 1 + 3 \cdot 2 + 4 \cdot 3 = 19$$

r_2

1	2	4	5
---	---	---	---

0

FILTER

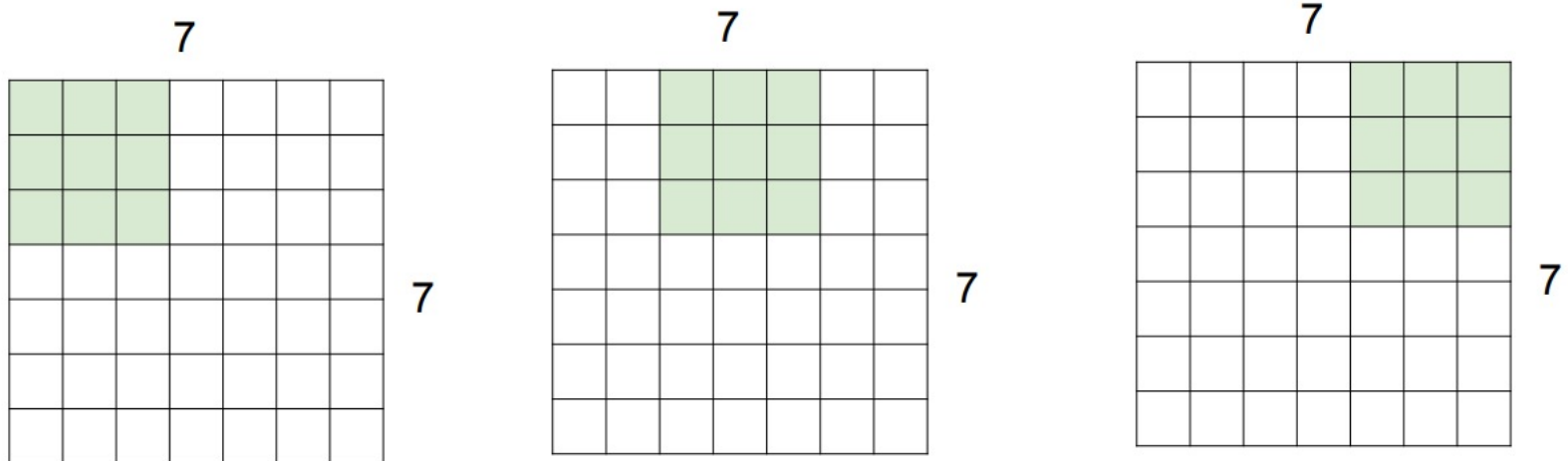
0	1	2	3
---	---	---	---

||

25

Convolutions with stride

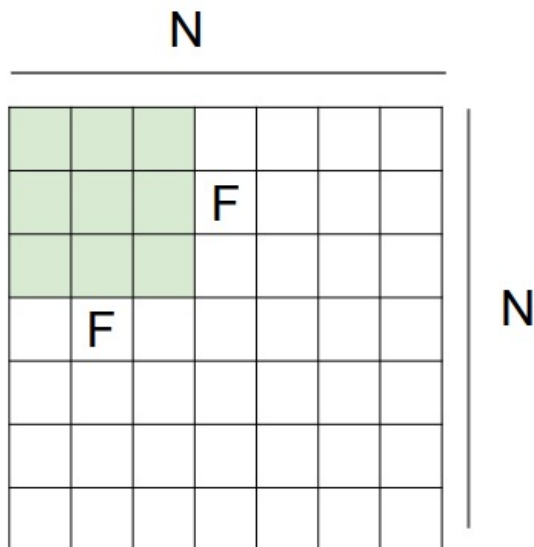
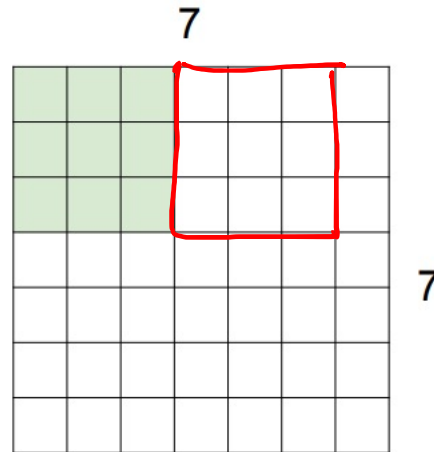
7x7 input (spatially)
assume 3x3 filter
applied **with stride 2**



OUTPUT: 3x3

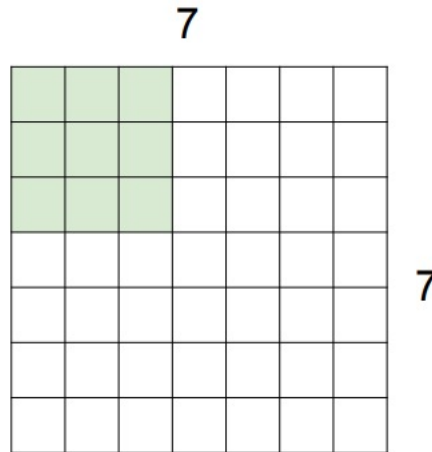
Convolutions with stride

7x7 input (spatially)
assume 3x3 filter
applied **with stride 3**



Convolutions with stride

7x7 input (spatially)
assume 3x3 filter
applied **with stride 3**

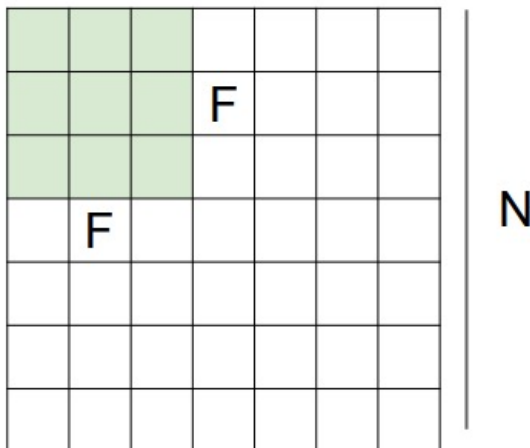


doesn't fit!
cannot apply 3x3 filter on
7x7 input with stride 3.

IF $N - F$ NOT DIVISIBLE BY STRIDE
ADD PADDING

$N = \text{INPUT SIZE}$

$F = \text{FILTERS}$
SIZE



Output size:
 $(N - F) / \text{stride} + 1$

e.g. $N = 7, F = 3$:

stride 1 $\Rightarrow (7 - 3) / 1 + 1 = 5$

stride 2 $\Rightarrow (7 - 3) / 2 + 1 = 3$

stride 3 $\Rightarrow (7 - 3) / 3 + 1 = 2.33 \therefore \backslash$

Padding

In practice: Common to zero pad the border

0	0	0	0	0	0			0
0								0
0								0
0								
0								
.								0
.								0
0								0
0	0	0				0	0	0

e.g. input 7x7

3x3 filter, applied with **stride 3**

pad with 1 pixel border => what is the output?

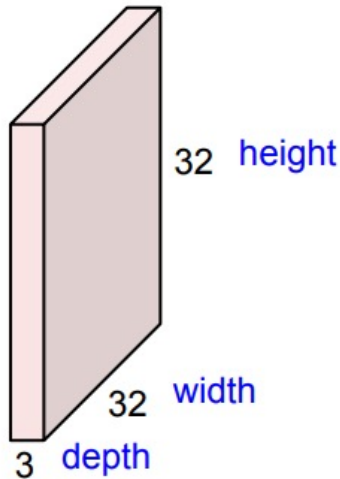
(recall:)

$$(N - F) / \text{stride} + 1$$

OUTPUT 3x3

Convolution Layer ^{3D}

32x32x^{RGB}3 image -> preserve spatial structure



Depth of filter = depth of input

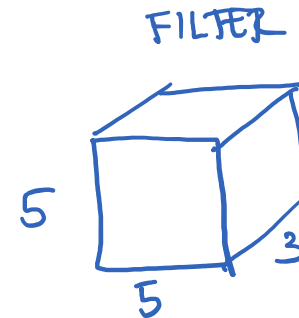
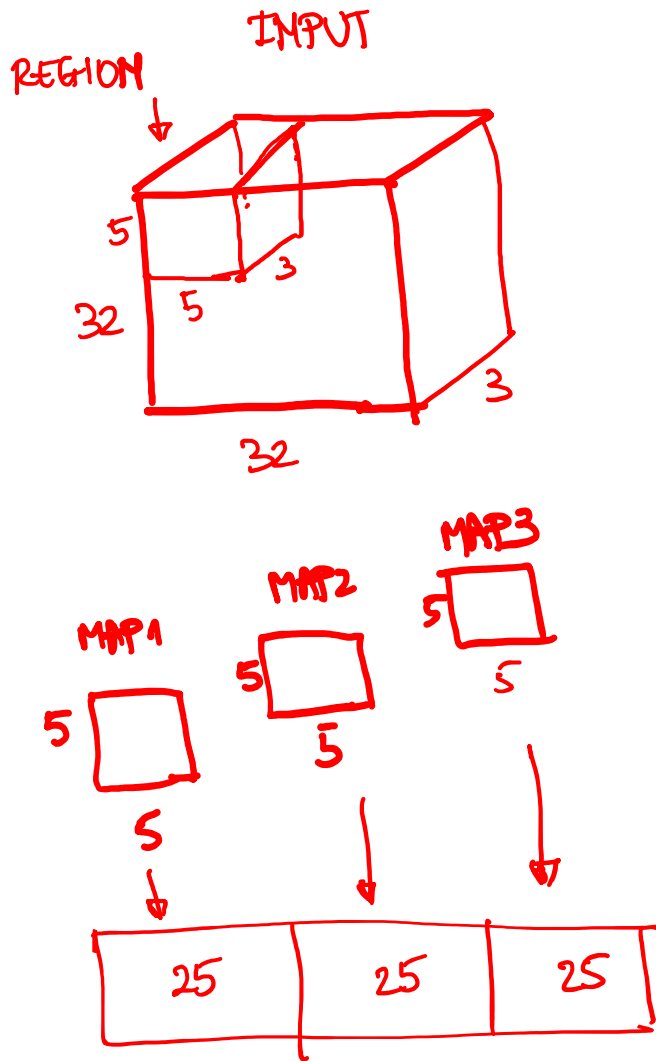
5x5x³ filter



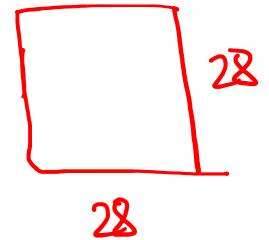
Convolve the filter with the image
i.e. "slide over the image spatially,
computing dot products"

- Depth of filter always depth of input
- Computation is based only on local information

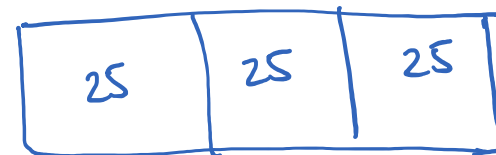
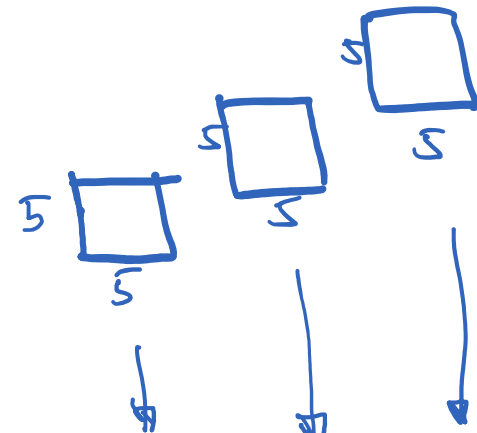
Convolution Operation



OUTPUT SIZE



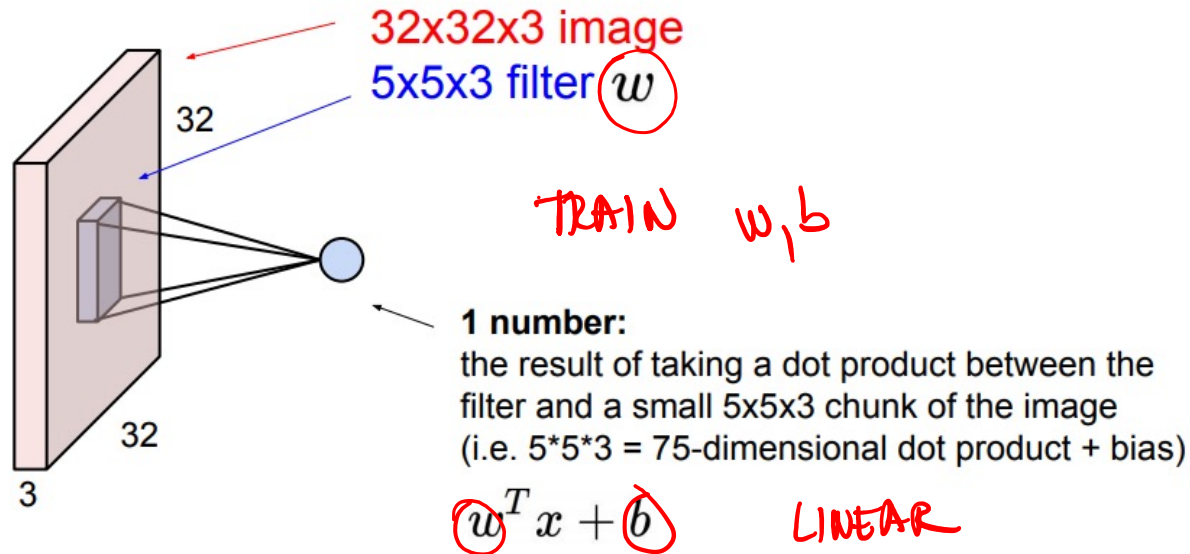
ACTIVATION
MAP
(ONE PER
FILTER)



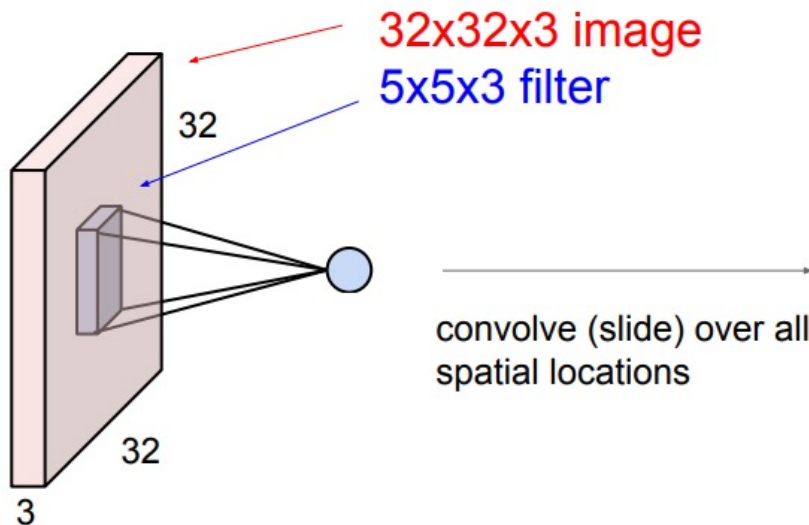
+BIAS

•
DOT PRODUCT

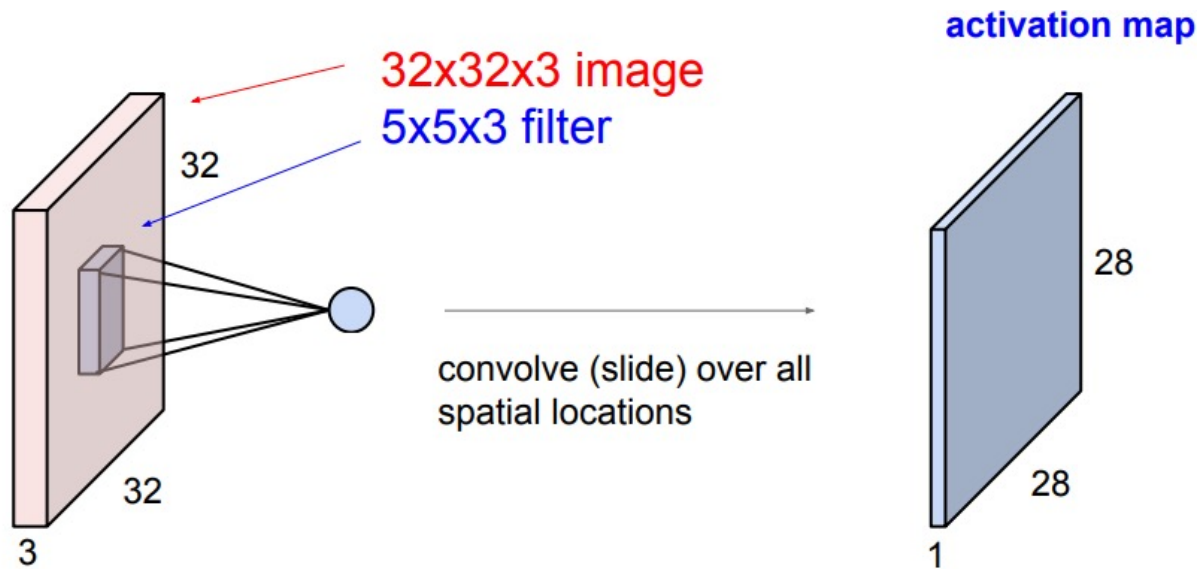
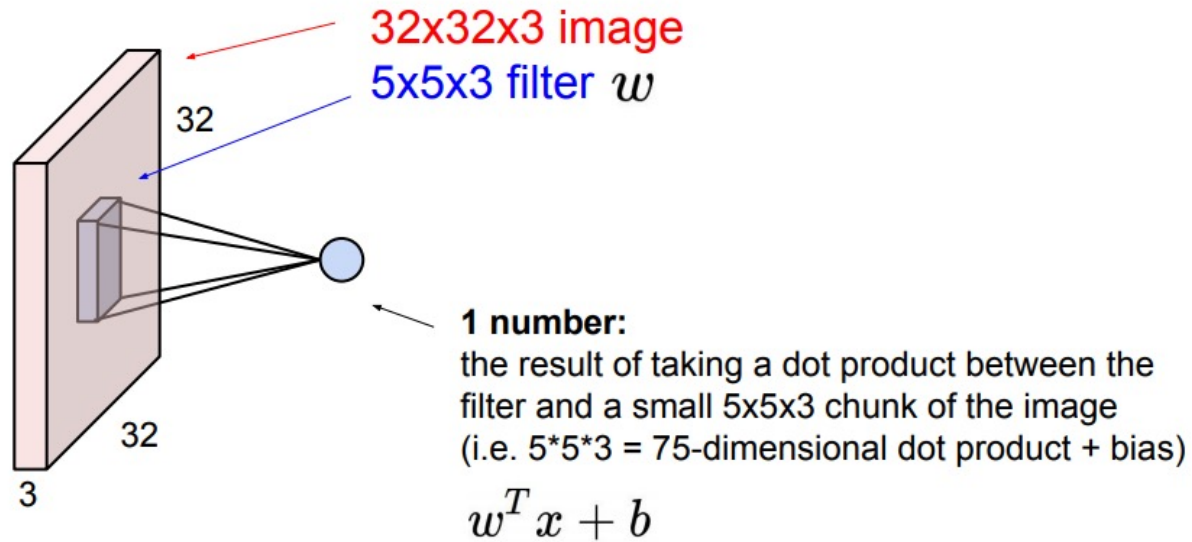
Convolution Layer



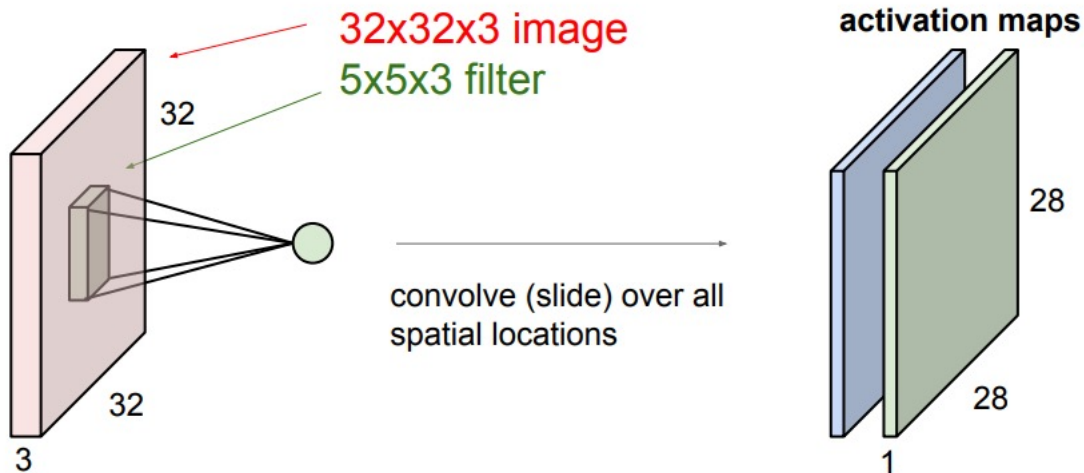
76 PARAMS



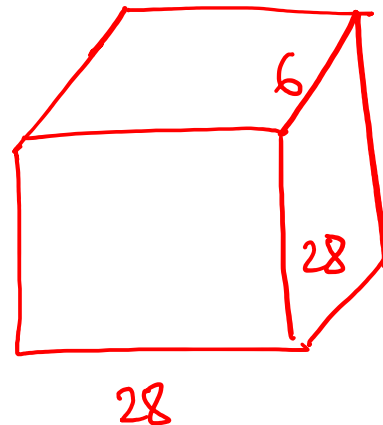
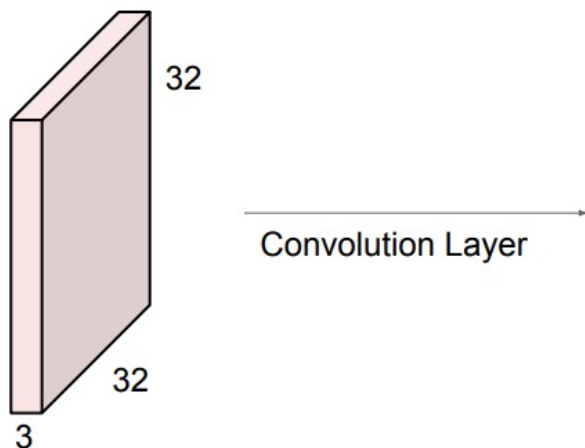
Convolution Layer



Convolution Layer



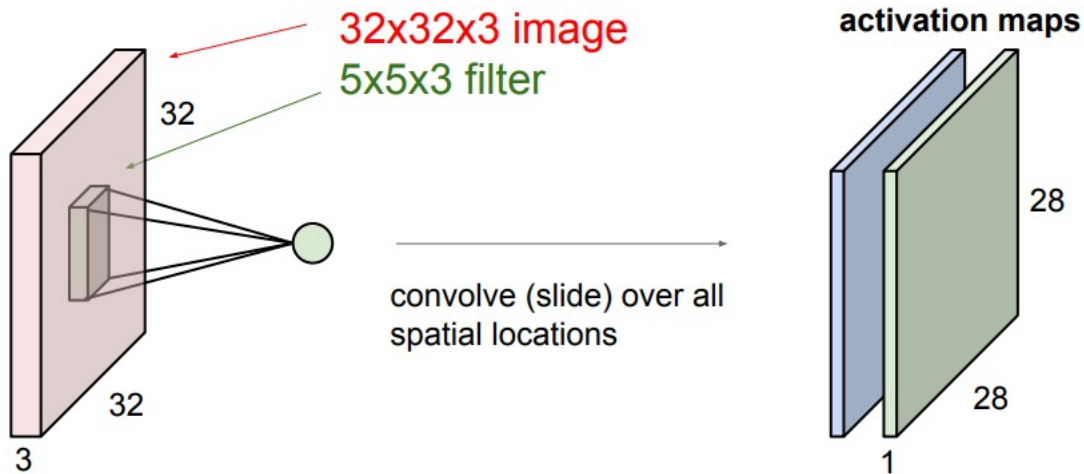
Second, green filter



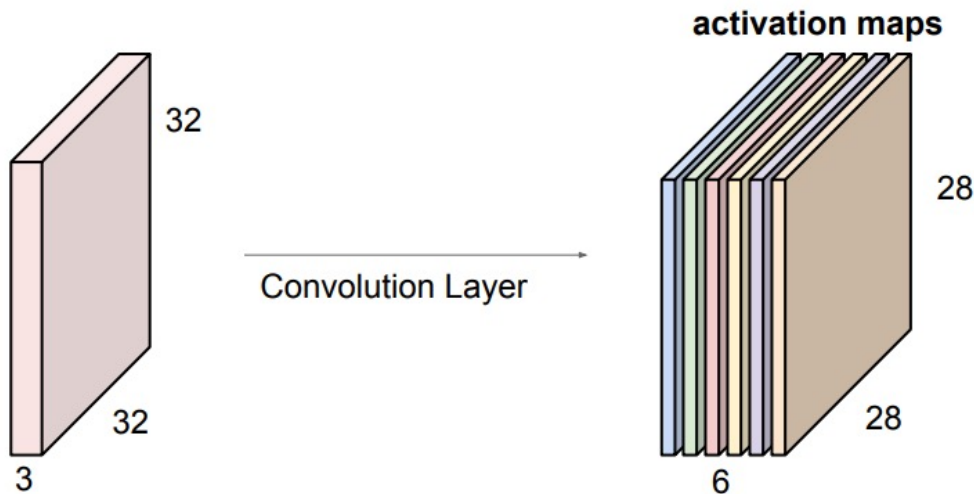
DEPTH = #FILTERS

||
6 filters
5x5x3

Convolution Layer



Second, green filter



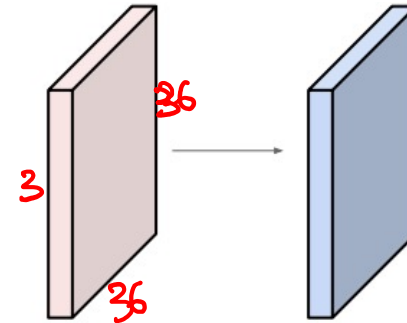
6 filters

Examples

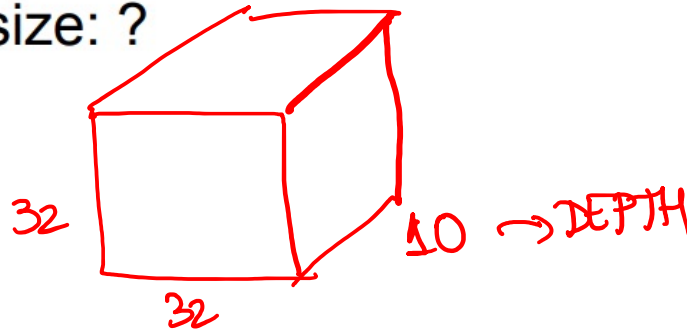
Examples time:

Input volume 36x36x3

10 5x5x3 filters with stride 1, ~~pad 2~~



Output volume size: ?



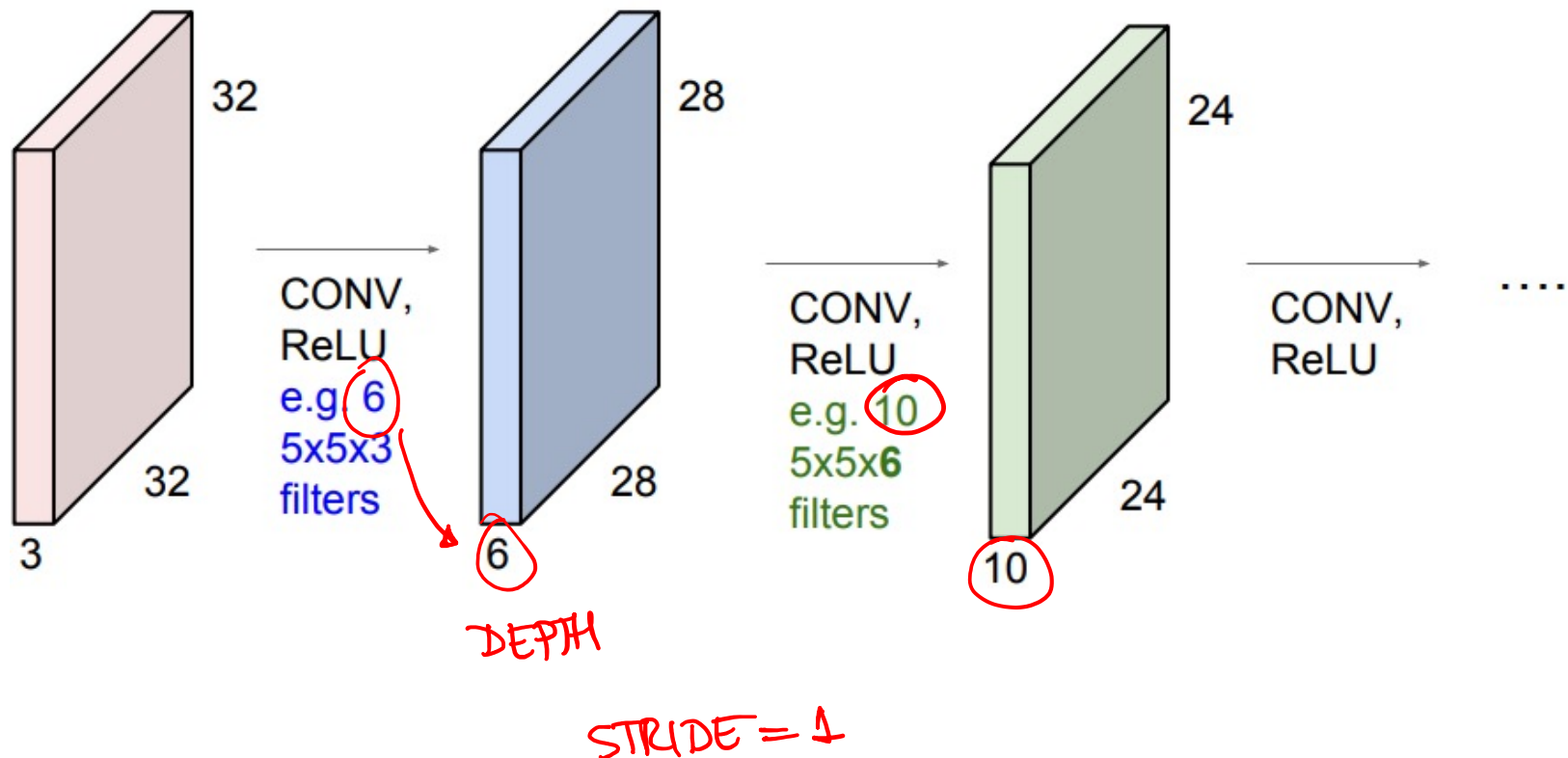
Number of parameters in this layer?

1 FILTER: $5 \times 5 \times 3 + 1 = 76$

10 FILTERS: 760

Convolutional Nets

Preview: ConvNet is a sequence of Convolution Layers, interspersed with activation functions



Convolution layer: Takeaways

- Convolution is a linear operation
 - Reduces parameter space of Feed-Forward Neural Network considerably
 - Capture locality of pixels in images
 - Smaller filters need less parameters
 - Multiple filters in each layer (computation can be done in parallel)
- Convolutions are followed by activation functions
 - Typically ReLU

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