DS 4400

Machine Learning and Data Mining I Spring 2021

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Outline

- Deep Learning
 - Motivation
 - Goals
- Deep Learning as representation learning
- Perceptron and its limitations
- Feed-forward neural networks

SVM Classifier

- Support Vector Classifier (SVC, linear SVM)
 - SVC classifier is linear combination of dot product between testing point and support vectors

$$-h(z) = \theta_0 + \sum_{i \in S} \alpha_i < z, x_i >$$

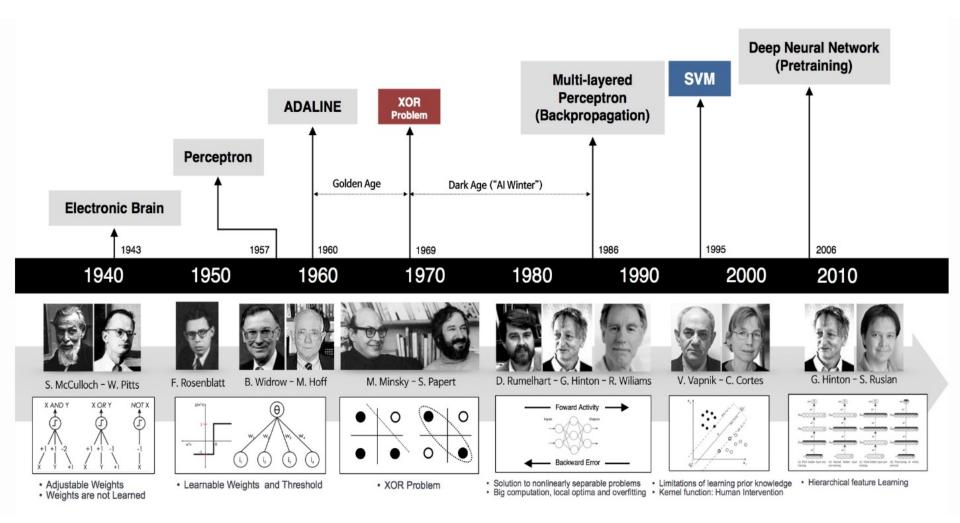
- Two methods to train:
 - Solve directly optimization problem to find maximum margin
 - Gradient descent with hinge loss objective
- SVM classifier
 - Select a kernel function K
 - SVM classifier is linear combination of kernel between testing point and support vectors

$$-h(z) = \theta_0 + \sum_{i \in S} \alpha_i K(z, x_i)$$

Comparing SVM with other classifiers

- SVM is resilient to outliers
 - Similar to Logistic Regression
 - LDA or kNN are not
- SVM can be trained with Gradient Descent
 - Hinge loss cost function
- Supports regularization
 - Can add penalty term (ridge or Lasso) to cost function
- Linear SVM is most similar to Logistic Regression

History of Deep Learning

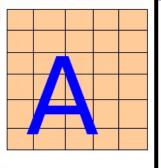


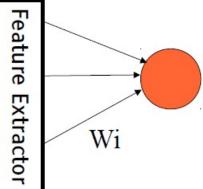
References

- Deep Learning books
 - https://d2l.ai/ (D2L)
 - https://www.deeplearningbook.org/ (advanced)
- Stanford notes on deep learning
 - http://cs229.stanford.edu/summer2020/cs229notes-deep_learning.pdf

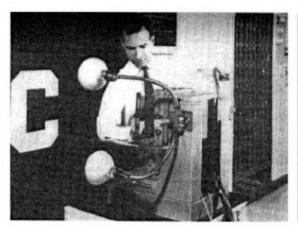
Before 2013

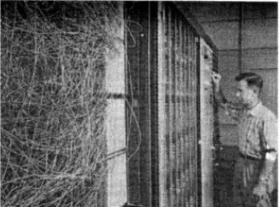
- The first learning machine: the Perceptron
 - Built at Cornell in 1960
- The Perceptron was a linear classifier on top of a simple feature extractor
- The vast majority of practical applications of ML today use glorified linear classifiers or glorified template matching.
- Designing a feature extractor requires considerable efforts by experts.

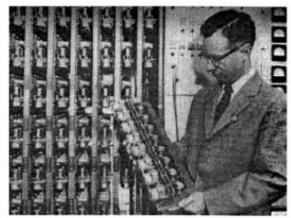




$$y=sign\left(\sum_{i=1}^{N}W_{i}F_{i}(X)+b\right)$$

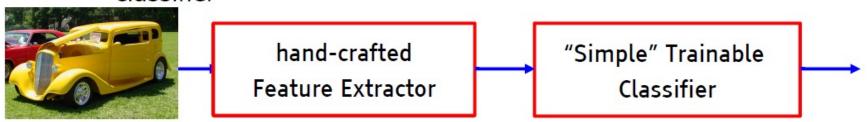




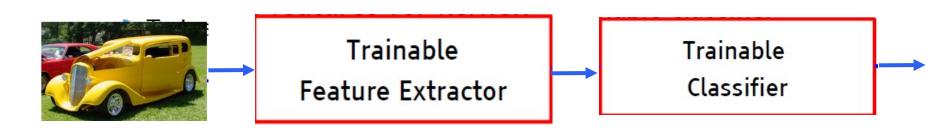


Deep Learning

- The traditional model of pattern recognition (since the late 50's)
 - Fixed/engineered features (or fixed kernel) + trainable classifier

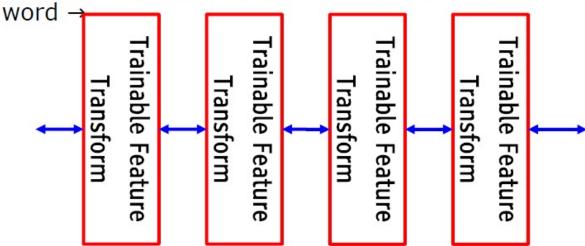


End-to-end learning / Feature learning / Deep learning

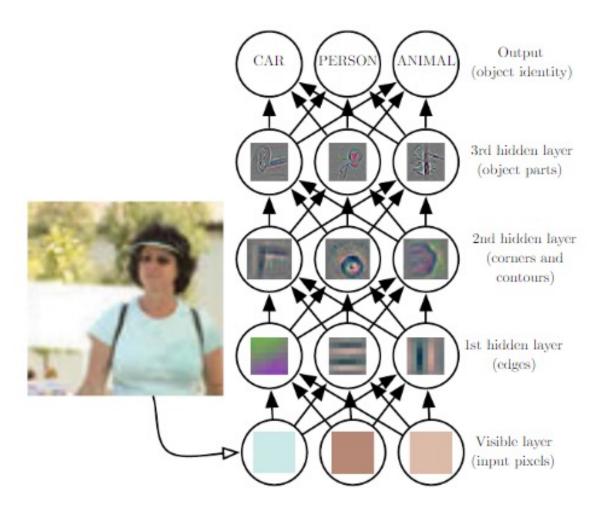


Trainable Feature Hierarchy

- Hierarchy of representations with increasing level of abstraction
- Each stage is a kind of trainable feature transform
- Image recognition
 - Pixel → edge → texton → motif → part → object
- Text
 - Character → word → word group → clause → sentence → story
- Speech
 - Sample → spectral band → sound → ... → phone → phoneme →

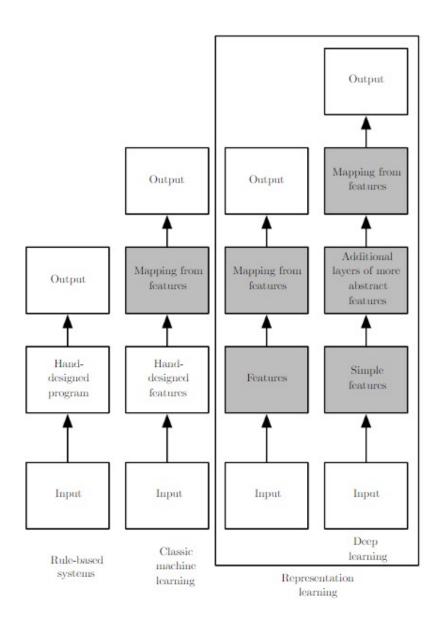


Learning Representations



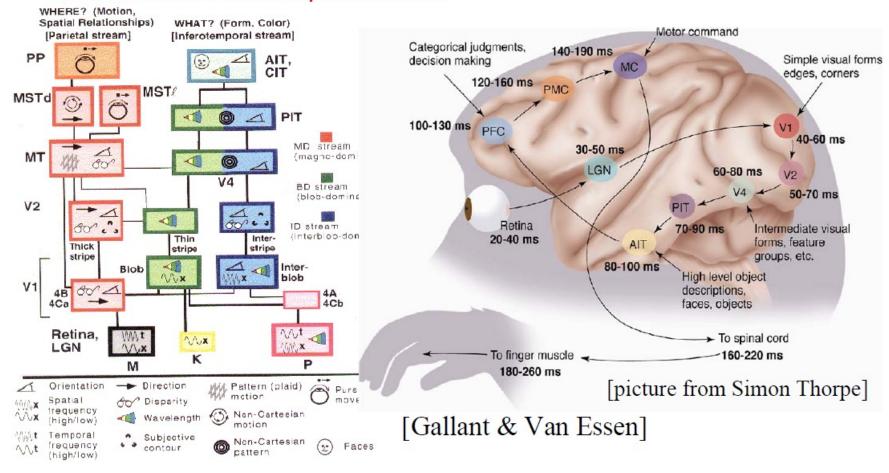
Deep Learning addresses the problem of learning hierarchical representations

Deep Learning vs Traditional Learning



The Visual Cortex is Hierarchical

- The ventral (recognition) pathway in the visual cortex has multiple stages
- Retina LGN V1 V2 V4 PIT AIT
- Lots of intermediate representations

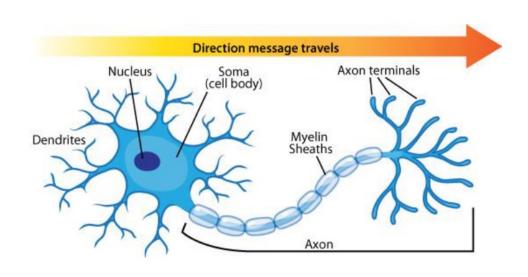


Neural Function

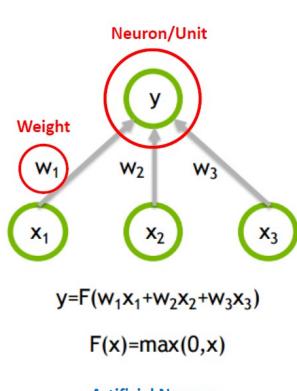
- Brain function (thought) occurs as the result of the firing of neurons
- Neurons connect to each other through synapses, which propagate action potential (electrical impulses) by releasing neurotransmitters
 - Synapses can be excitatory (potential-increasing) or inhibitory (potential-decreasing), and have varying activation thresholds
 - Learning occurs as a result of the synapses' plasticicity:
 They exhibit long-term changes in connection strength
- There are about 10¹¹ neurons and about 10¹⁴ synapses in the human brain!

Analogy to Human Brain

Human Brain



Biological Neuron

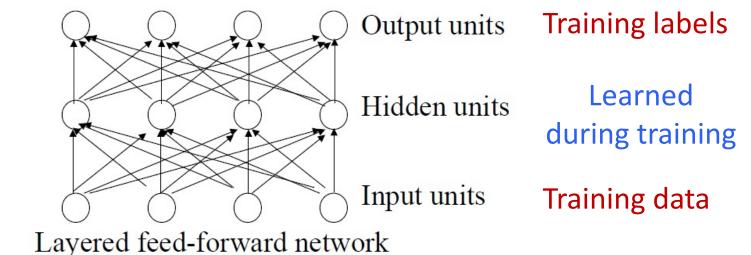


Artificial Neuron

Neural Networks

- · Origins: Algorithms that try to mimic the brain.
- Very widely used in 80s and early 90s; popularity diminished in late 90s.
- Recent resurgence: State-of-the-art technique for many applications
- Artificial neural networks are not nearly as complex or intricate as the actual brain structure

Neural Networks



- Neural networks are made up of nodes or units, connected by links
- Each link has an associated weight and activation level
- Each node has an input function (typically summing over weighted inputs), an activation function, and an output

Example

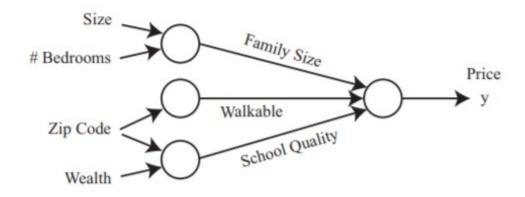
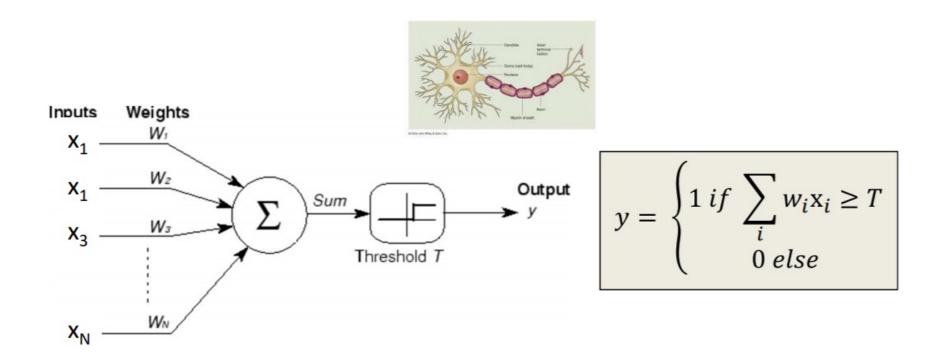


Figure 2: Diagram of a small neural network for predicting housing prices.

Intermediate Features: Family size, Walkable, School quality

- Provide as input only training data: input and label
- Neural Networks automatically learn intermediate features!

Perceptron



- A threshold unit
 - "Fires" if the weighted sum of inputs exceeds a threshold

The Perceptron

$$h(x) = \operatorname{sign}(\theta^{\mathsf{T}} x)$$
 where $\operatorname{sign}(z) = \begin{cases} 1 & \text{if } z \ge 0 \\ -1 & \text{if } z < 0 \end{cases}$

• The perceptron uses the following update rule each time it receives a new training instance (x_i, y_i)

$$\theta_j \leftarrow \theta_j - \frac{1}{2} (h_\theta(x_i) - y_i) x_{ij}$$

- If the prediction matches the label, make no change
- Otherwise, adjust heta

The Perceptron

• The perceptron uses the following update rule each time it receives a new training instance (x_i, y_i)

$$\theta_j \leftarrow \theta_j - \frac{1}{2} (h_{\theta}(x_i) - y_i) x_{ij}$$
either 2 or -2

• Re-write as

$$\theta_j \leftarrow \theta_j + y_i x_{ij}$$

(only upon misclassification)

Perceptron Rule: If x_i is misclassified, do $\theta \leftarrow \theta + y_i x_i$

Online Perceptron

```
Let \theta \leftarrow [0,0,...,0]
Repeat:
Receive training example (x_i,y_i)
If y_i\theta^Tx_i \leq 0 // prediction is incorrect \theta \leftarrow \theta + y_i x_i
Until stopping condition
```

Online learning – the learning mode where the model update is performed each time a single observation is received

Batch learning – the learning mode where the model update is performed after observing the entire training set

Batch Perceptron

```
Let \theta \leftarrow [0,0,...,0]

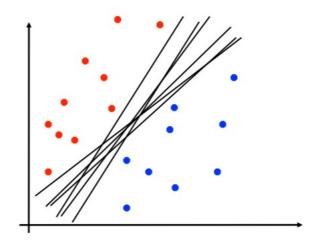
Repeat: \Delta = [0,0,...,0]

For i=1 to N // Consider all training examples \text{If } y_i \theta^T x_i \leq 0 \qquad \text{// Prediction is incorrect} \Delta \leftarrow \Delta + y_i \ x_i. \qquad \text{// Accumulate all errors} \theta \leftarrow \theta + \frac{\Delta}{N} \qquad \text{// Parameter update rule} Until stopping condition
```

 Guaranteed to find separating hyperplane if data is linearly separable

Perceptron Limitations

- Is dependent on starting point
- It could take many steps for convergence
- Perceptron can overfit
 - Move the decision boundary for every example



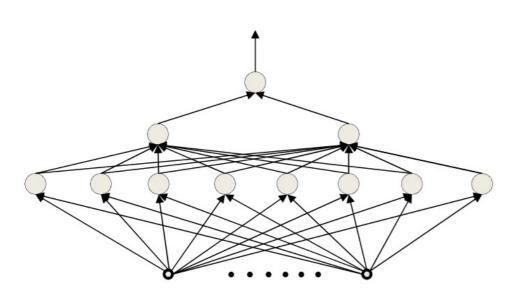
Which of this is optimal?

History of Perceptrons

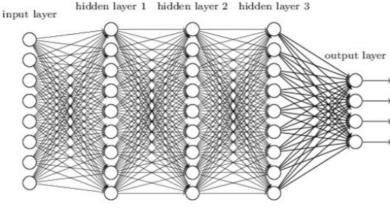
- They were popularised by Frank Rosenblatt in the early 1960's.
 - They appeared to have a very powerful learning algorithm.
 - Lots of grand claims were made for what they could learn to do.
- In 1969, Minsky and Papert published a book called "Perceptrons" that analysed what they could do and showed their limitations.
 - Many people thought these limitations applied to all neural network models.
- The perceptron learning procedure is still widely used today for tasks with enormous feature vectors that contain many millions of features.

They are the basic building blocks for Deep Neural Networks

Multi-Layer Perceptron



Deep neural network



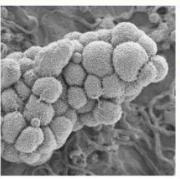
- A network of perceptrons
 - Generally "layered"



Deep Learning Applications

DEEP LEARNING EVERYWHERE











INTERNET & CLOUD

Image Classification Speech Recognition Language Translation Language Processing Sentiment Analysis Recommendation MEDICINE & BIOLOGY

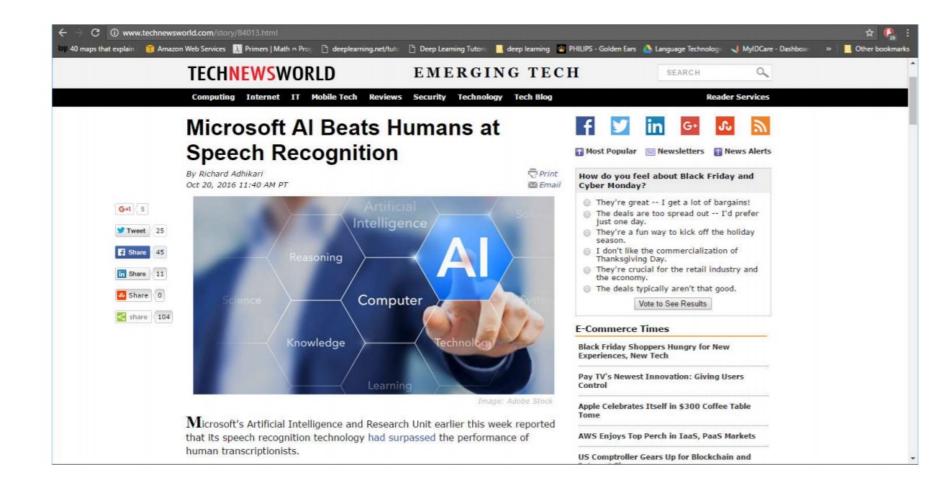
Cancer Cell Detection Diabetic Grading Drug Discovery MEDIA & ENTERTAINMENT

Video Captioning Video Search Real Time Translation SECURITY & DEFENSE

Face Detection Video Surveillance Satellite Imagery **AUTONOMOUS MACHINES**

Pedestrian Detection Lane Tracking Recognize Traffic Sign

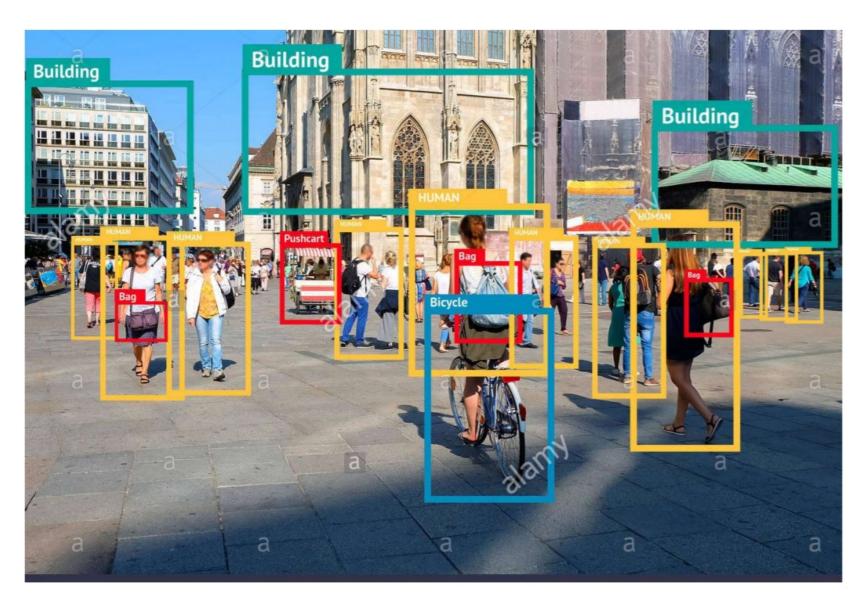
Success stories: Speech recognition



Success stories: Machine Translation



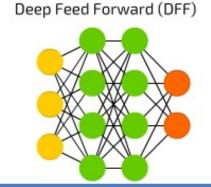
Success stories: Image segmentation



Neural Network Architectures

Feed-Forward Networks

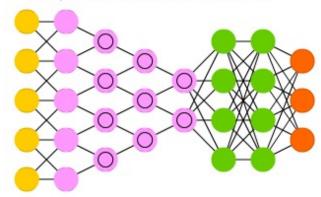
 Neurons from each layer connect to neurons from next layer



Convolutional Networks

- Includes convolution layer for feature reduction
- Learns hierarchical representations

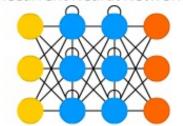
Deep Convolutional Network (DCN)



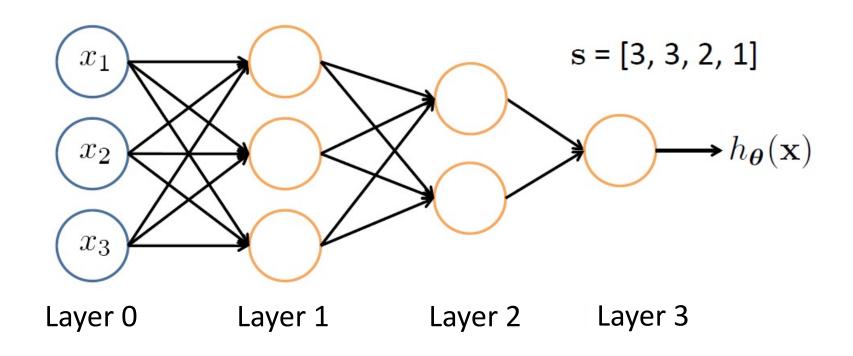
Recurrent Networks

- Keep hidden state
- Have cycles in computational graph

Recurrent Neural Network (RNN)



Feed-Forward Networks



 ${\it L}$ denotes the number of layers

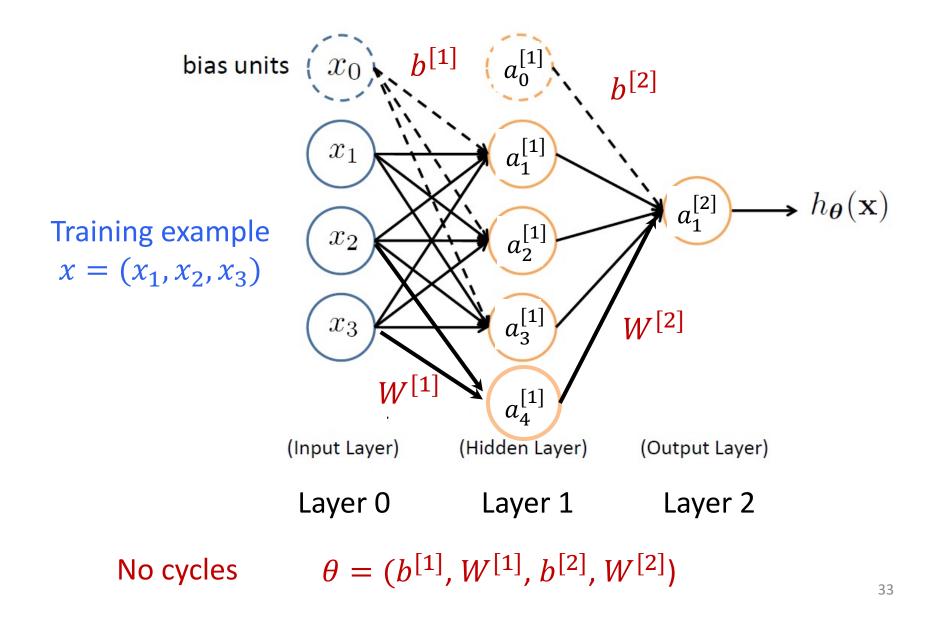
 $\mathbf{s} \in \mathbb{N}^{+L}$ contains the numbers of nodes at each layer

- Not counting bias units
- Typically, $s_0=d$ (# input features) and $s_{L-1}=K$ (# classes)

Feed-Forward NN

- Hyper-parameters
 - Number of layers
 - Architecture (how layers are connected)
 - Number of hidden units per layer
 - Number of units in output layer
 - Activation functions
- Other
 - Initialization
 - Regularization

Feed-Forward Neural Network



Vectorization

$$z_1^{[1]} = W_1^{[1]} \quad x + b_1^{[1]} \quad \text{and} \quad a_1^{[1]} = g(z_1^{[1]})$$

$$\vdots \qquad \qquad \vdots \qquad \qquad \vdots$$

$$z_4^{[1]} = W_4^{[1]} \quad x + b_4^{[1]} \quad \text{and} \quad a_4^{[1]} = g(z_4^{[1]})$$

$$\underbrace{\begin{bmatrix} z_1^{[1]} \\ \vdots \\ \vdots \\ z_4^{[1]} \end{bmatrix}}_{z^{[1]} \in \mathbb{R}^{4 \times 1}} = \underbrace{\begin{bmatrix} -W_1^{[1]} \\ -W_2^{[1]} \\ \vdots \\ -W_4^{[1]} \end{bmatrix}}_{W^{[1]} \in \mathbb{R}^{4 \times 3}} \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_{x \in \mathbb{R}^{3 \times 1}} + \underbrace{\begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ \vdots \\ b_4^{[1]} \end{bmatrix}}_{b^{[1]} \in \mathbb{R}^{4 \times 1}}$$

$$z^{[1]} = W^{[1]}x + b^{[1]}$$

 $a^{[1]} = g(z^{[1]})$

Linear

Non-Linear

Review

- Perceptrons are limited in their ability to learn
- Feed-Forward Neural Networks are the most common neural networks architectures
 - Fully connected networks are called Multi-Layer
 Perceptron
- Input, output, and hidden layers
 - Linear matrix operations followed by non-linear activations at every layer
- Activations:
 - Examples: ReLU, sigmoid
 - Non-linear function

Acknowledgements

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 - Andrew Ng
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 - David Sontag
 - Andrew Moore
 - Yann LeCun
- Thanks!